



# TESTS OF THE GRAVITATIONAL INVERSE-SQUARE LAW

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**ABSTRACT:** We review recent experimental tests of the gravitational inverse-square law and the wide variety of theoretical considerations that suggest the law may break down in experimentally accessible regions.

## CONTENTS

INTRODUCTION . . . . .	3
<i>Background</i> . . . . .	3
<i>Scope of This Review</i> . . . . .	7
THEORETICAL SPECULATIONS . . . . .	8
<i>Unifying Gravity with Particle Physics: Two Hierarchy Problems</i> . . . . .	8
<i>Extra Dimensions and TeV-scale Unification of Gravity</i> . . . . .	13
<i>Infinite-Volume Extra Dimensions</i> . . . . .	20
<i>Exchange Forces from Conjectured New Bosons</i> . . . . .	22
<i>Attempts to Solve the Cosmological-Constant Problem</i> . . . . .	29

EXPERIMENTAL CHALLENGES . . . . .	32
<i>Signals</i> . . . . .	32
<i>Noise Considerations</i> . . . . .	33
<i>Backgrounds</i> . . . . .	35
<i>Experimental Strategies</i> . . . . .	39
EXPERIMENTAL RESULTS . . . . .	40
<i>Low-Frequency Torsion Oscillators</i> . . . . .	40
<i>High-Frequency Torsion Oscillators</i> . . . . .	45
<i>Microcantilevers</i> . . . . .	47
<i>Casimir Force Experiments</i> . . . . .	50
<i>Astronomical Tests</i> . . . . .	54
CONCLUSIONS . . . . .	56
<i>Summary of Experimental Results</i> . . . . .	56
<i>Prospects for Improvements</i> . . . . .	57
<i>What if a Violation of the <math>1/r^2</math> Law Were Observed?</i> . . . . .	60
ACKNOWLEDGMENTS . . . . .	61
LITERATURE CITED . . . . .	61

## 1 INTRODUCTION

### 1.1 *Background*

Gravitation was the first of the four known fundamental interactions to be understood quantitatively and the first “grand unification” in physics. Isaac Newton’s Theory of Universal Gravitation connected terrestrial phenomena (the “falling apple”) with astronomical observations (the “falling Moon” and Kepler’s Laws). This theory stood virtually unchallenged until Albert Einstein developed his rel-

ativistic theory of gravitation in 1917. Since then, General Relativity has passed all experimental tests and is today the standard model of gravitation. Yet some three centuries after Newton, gravitation remains one of the most puzzling topics in physics. Recently, a completely unexpected and fundamentally new gravitational property was discovered using distant Type Ia supernovae: the apparent *acceleration* of the Hubble expansion (1, 2), which is as yet unexplained. Furthermore, gravitation is not included, and in fact not *includable*, in the imposing quantum field theory that constitutes the standard model of particle physics.

There is a broad consensus that the two standard models are incompatible. The strong, weak, and electromagnetic interactions are explained as results of the quantum exchange of virtual bosons, whereas the gravitational interaction is explained as a classical consequence of matter and energy curving spacetime. Because quantum field theories cannot describe gravitation and General Relativity predicts an infinite spacetime curvature at the center of a black hole, neither of these two standard models is likely to be truly fundamental.

Connecting gravity with the rest of physics is clearly the central challenge of fundamental physics, and for the first time we have a candidate theory (string or M-theory) that may unify gravitation with particle physics. But the remaining theoretical problems have focused attention on possible new phenomena that could show up as deviations from the familiar inverse-square law (ISL) of gravity, generally at length scales less than a few millimeters, but sometimes also at astronomical or even cosmological distances. We review these speculations in Section 2.

Although it is conventionally assumed that the ISL should be valid for separations from infinity to roughly the Planck length ( $R_P = \sqrt{G\hbar/c^3} = 1.6 \times 10^{-35}$

m), until a few years ago this assumption had only been precisely tested for separations ranging from the scale of the solar system down to a few millimeters. The reasons for this are obvious: On the one hand, there are no independently known mass distributions on length scales larger than the solar system, and on the other hand, it is difficult to get enough matter in close enough proximity to obtain a background-free gravitational signal at length scales smaller than 1 mm. This contrasts strongly with Coulomb's Law (and its electroweak generalization), which has been tested for separations down to  $10^{-18}$  m in  $e^+e^-$  leptonic interactions at high-energy colliders (3). Although Coulomb's Law has not been experimentally verified at large length scales (relative to laboratory dimensions), a null-type laboratory measurement looking for effects of the galactic electromagnetic vector potential,  $A$ , rules out deviations due to a finite photon mass for length scales up to  $\sim 2 \times 10^{10}$  m (4).

### 1.1.1 Parameterizations

Historically, experimental tests of Coulomb's and Newton's inverse-square laws were used to set limits on violations that, for gravity, took the form

$$F(r) = G \frac{m_1 m_2}{r^{2+\epsilon}} . \quad (1)$$

From the perspective of Gauss's Law, the exponent 2 is a purely geometrical effect of three space dimensions, so this parameterization was not well-motivated theoretically. Instead, it is now customary to interpret tests of the ISL as setting limits on an additional Yukawa contribution to the familiar  $1/r^2$  contribution, which in the gravitational case creates a potential

$$V(r) = -G \frac{m_1 m_2}{r} \left[ 1 + \alpha e^{-r/\lambda} \right] , \quad (2)$$

where  $\alpha$  is a dimensionless strength parameter and  $\lambda$  is a length scale or range. The Yukawa contribution is the static limit of an interaction due to the exchange of virtual bosons of mass  $m_b = \hbar/(\lambda c)$ , where  $m_b$  is the boson mass; the Yukawa form is also useful in other contexts (see Section 2.2.1).

Some investigators (see, e.g., (5)) have considered the possibility that a nonzero graviton mass could lead to a “pure Yukawa” gravitational potential  $V(r) = -Gm_1m_2e^{-r/\lambda}/r$ , recognizing that this phenomenological form does not have a well-defined theoretical foundation (see ref. (6) for a different approach to the implications of a nonzero gravitational mass). Others have considered power-law modifications to the ISL (7):

$$V(r) = -G \frac{m_1 m_2}{r} \left[ 1 + \alpha_N \left( \frac{r_0}{r} \right)^{N-1} \right], \quad (3)$$

where  $\alpha_N$  is a dimensionless constant and  $r_0$  corresponds to a new length scale associated with a non-Newtonian process. Terms with  $N = 2$  and  $N = 3$  may be generated by the simultaneous exchange of two massless scalar and two massless pseudoscalar particles, respectively (8, 9, 10), while  $N = 5$  may be generated by the simultaneous exchange of two massless axions (11) or a massless neutrino-antineutrino pair (12).

In this review, we focus on the parameterization of Equation 2; any experiment that detects a violation of the ISL will indicate a strength,  $\alpha$ , and a length scale,  $\lambda$ , that characterizes the violation. Once a violation is detected, it will become necessary to determine the functional form of the violation. The parameterization of Equation 2 has strong implications for experimental tests of the ISL. Any one test of the law necessarily covers a limited range of length scales. Suppose, for example, one performs a Keplerian test, comparing the orbits of two planets orbiting a common sun. Clearly, the test is insensitive to values of  $\lambda$  much less

than the orbit radius of the inner planet. It is also insensitive to ranges of  $\lambda$  much larger than the orbit radius of the outer planet because both planets simply feel a renormalized Newton constant  $\tilde{G} = G(1 + \alpha)$ . Consequently, a great variety of experiments is needed to effectively explore a wide variety of length scales. This contrasts with limits on Yukawa interactions from “equivalence principle” tests, where a single experimental result for a composition-dependent acceleration difference typically provides a constraint on  $\alpha$  for values of  $\lambda$  ranging from the length scale of the attractor to infinity (see, e.g., (13)).

## 1.2 *Scope of This Review*

This review concentrates on experimental tests of the ISL at length scales of millimeters or less, and on the wide range of theoretical developments suggesting that new phenomena may occur in this regime. We also discuss speculations about possible ISL violations at much larger length scales that could have important cosmological implications. A extensive review of experimental results at longer length scales (14) appeared in 1999; we update it in Section 4.5 below. A review of extra “gravitational” dimensions, with emphasis on collider signatures, has recently appeared in this journal (15). A recent review of tests of the ISL from microns to centimeters is Reference (16). Our review is focused on work done since 1995 and should be current as of January 2003. An earlier review (13) covered spin-dependent forces that we do not consider here.

## 2 THEORETICAL SPECULATIONS

### 2.1 *Unifying Gravity with Particle Physics: Two Hierarchy Problems*

The two greatest triumphs of twentieth-century physics are general relativity and quantum mechanics. However, we do not currently know how to link these two theories, or how to do calculations consistently in situations where both gravity and quantum effects are important, such as near the Big Bang and the cores of black holes. Clearly general relativity must be contained in a more fundamental quantum theory that would allow sensible calculations even in extreme conditions. However, attempts to quantize general relativity have been plagued with difficulties. Although one can construct an effective quantum field theory of gravity and particle physics that is sufficiently accurate for many applications, the theory is infamously “nonrenormalizable” or nonpredictive—an infinite number of free parameters are needed to describe quantum effects at arbitrarily short distances to arbitrary precision.

All known nongravitational physics is includable within the standard model of particle physics—a quantum field theory in which the weak and electromagnetic interactions are unified into a single framework known as the electroweak theory. Symmetry between the weak and electromagnetic interactions is manifest above a scale of roughly 100 GeV. This unification scale, where the electroweak symmetry is spontaneously broken, is known as the electroweak scale. The electroweak scale is set by a condensate of a scalar field known as the Higgs field that has a negative mass-squared term of order  $(100 \text{ GeV})^2$  in its potential. All three forces of the standard model, the electromagnetic, weak, and strong interactions, are similarly unifiable into a simple group with a single coupling at the fantastically high energy

scale of  $10^{16}$  GeV. This “grand” unified theory (GUT) explains the quantization of electric charge and, provided there exists a new symmetry between fermions and bosons known as supersymmetry, predicts the observed value for the relative strengths of the weak and electromagnetic couplings. But supersymmetry has not yet been observed in nature and, if present, must be spontaneously broken. Supersymmetry and GUTs are reviewed in References (17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28).

Intriguingly, the Planck scale,  $M_P = \sqrt{\hbar c/G}$ , at which quantum-gravity effects must become important,  $M_P c^2 = 1.2 \times 10^{19}$  GeV, is rather close to the apparent unification scale of the other forces. This hints that all belong together in a unified framework containing a fundamental scale of order  $M_P$ . Motivated by GUTs, the conventional view is that the phenomenal weakness of gravity at accessible energies— $10^{32}$  times weaker than the other forces at the electroweak scale—is due to the small masses of observed particles relative to  $M_P$ .

In the standard model, particle masses derive from the Higgs condensate. The tremendous discrepancy between the scale of this condensate and the presumed fundamental scale of physics is known as the *gauge-hierarchy problem*. In the minimal standard model, the smallness of the Higgs mass-squared parameter relative to the GUT or Planck scales violates a principle known as “naturalness”—renormalized values of parameters that receive large quantum corrections should not be much smaller than the size of the corrections. The Higgs mass squared receives corrections proportional to the cutoff or maximum scale of validity of the theory. Naturalness would therefore demand that to describe physics at energies higher than about 1 TeV, the standard model should be contained within a more fundamental theory in which the quantum corrections to the Higgs mass

are suppressed. An example of such a theory is a supersymmetric extension of the standard model. In theories with spontaneously or softly broken supersymmetry, the quantum corrections to scalar masses are proportional to the supersymmetry-breaking scale. Provided the supersymmetry-breaking scale is of order 100 GeV, the electroweak scale is natural, and the hierarchy question is why the supersymmetry-breaking scale is so small compared with  $M_P$ . This latter problem is theoretically tractable; in many supersymmetric models, the scale of supersymmetry breaking is proportional to exponentially small, nonperturbative quantum effects (29, 30).

A second, and much bigger, hierarchy problem is known as the *cosmological-constant problem*. The strong observational evidence (1, 2) that the expansion of the universe is accelerating can be explained by a nonvanishing cosmological constant. The concordance of cosmological data indicates (31) that the universe is filled with a vacuum-energy density  $\rho_{\text{vac}} \sim 0.7\rho_c$ , where  $\rho_c$  is the critical density  $3H^2c^2/(8\pi G)$  and  $H$  is the present value of the Hubble constant. This gives  $\rho_{\text{vac}} \sim 4 \text{ keV/cm}^3$ , which corresponds to an energy scale  $\sqrt[4]{(\hbar c)^3 \rho_{\text{vac}}} \approx 2 \text{ meV}$  or a length scale  $\sqrt[4]{(\hbar c)/\rho_{\text{vac}}} \sim 100 \text{ }\mu\text{m}$ . Such a small energy density is particularly puzzling because the quantum corrections to the vacuum energy density from particle physics scale as the fourth power of the cutoff of the effective theory. Such a cutoff might be provided by new physics in the gravitational sector. The energy scale of new gravitational physics has been presumed to be around  $M_P$ , which would imply a cosmological constant  $10^{120}$  times larger than observed. The success of the particle physics standard model at collider energy scales is inconsistent with a cutoff lower than 1 TeV. Even a relatively low TeV cutoff gives a theoretical contribution to the cosmological constant that is some  $10^{60}$  times

larger than experiment. References (32) and (33) conjecture that this monstrous discrepancy could be eliminated with a much lower cutoff for the gravitational sector of the effective theory, around 1 meV, corresponding to new gravitational physics at a distance of about  $100 \mu\text{m}$ . The theoretical framework for such a low gravity scale is necessarily very speculative. However, just as the gauge hierarchy compels experimental exploration of the TeV scale, the cosmological-constant problem strongly motivates submillimeter-scale tests of gravity.

General relativity itself gives indications that the theory of quantum gravity is radically different from a conventional quantum field theory. For instance, in theories of gravity, the concept of entropy must be generalized because entropy cannot be an extensive quantity scaling like volume. In fact, strong evidence favors an upper bound on the entropy of any region that scales as the surface area of the boundary of the region (34, 35, 36). A further conjecture, the “holographic principle,” suggests that this entropy bound indicates that the fundamental degrees of freedom of a gravitational theory can actually be formulated in a lower-dimensional theory. Reference (37) reviews these ideas and their subsequent development.

M-theory is a popular candidate for a theory of quantum gravity. This theory was called string theory when it was believed that its fundamental degrees of freedom were one-dimensional objects propagating in a 10-dimensional spacetime. Six of these dimensions were assumed to be rolled up into a compact manifold of size  $\sim R_P$  and unobservable. We now know that “string” theory necessarily contains many types of objects, known as “branes” or “ $p$ -branes,” where  $p$ , the number of spatial dimensions of the  $p$ -brane, can be anywhere from 0 to 9. This realization has revolutionized our understanding of string theory. Furthermore,

string theory is “dual,” or physically equivalent as a quantum theory, to an 11-dimensional theory known as M-theory. There is much theoretical evidence that all known consistent string theories, as well as 11-dimensional supergravity, are just weakly coupled limits in different vacua of a *single* theory of quantum gravity.

*Extra* dimensions might seem to contradict the holographic assertion that the fundamental theory is actually *lower*-dimensional. However, as comprehensively reviewed in Reference (38), the discovery that string theory on certain spacetimes with  $n$  noncompact dimensions is dual to a nongravitational gauge theory with  $n - 1$  dimensions provides additional theoretical evidence for holography, as well as for string theory. Strings, M-theory, p-branes, and duality have been reviewed extensively (39, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55) and are the subject of several excellent textbooks (40, 41).

Until recently, it was believed that experimental verification of a theory of quantum gravity was out of the question, due to the impossibly short distance scale at which quantum gravitational effects are known to be important. Furthermore, string theory contains a stupendous number of vacua—with no known principle for selecting the one we should live in—and so appears to have limited predictive power. Its chief phenomenological success to date is that in many of these vacua, the low-energy effective theory approximately resembles our world, containing the fields of the standard model and gravity propagating in four large dimensions. A major unsolved difficulty is that all known vacua are supersymmetric, although there are a variety of conceivable ways for the supersymmetry to be broken by a small amount.

As we discuss below, although string theory makes no unique prediction, all known ways of rendering our observations compatible with string theory lead

to new, dramatic signals in feasible experiments. In particular, the discovery of branes has led to new possibilities for explaining the gauge hierarchy and the cosmological constant. Many of these can be tested in measurements of gravity at submillimeter scales, or in searches for small deviations from general relativity at longer distances.

## 2.2 *Extra Dimensions and TeV-scale Unification of Gravity*

### 2.2.1 “Large” extra dimensions

It is usually assumed that the Planck scale is an actual physical scale, as is the weak scale, and that the gauge-hierarchy problem is to explain the origin of two vastly disparate scales. However, Arkani-Hamed, Dimopoulos and Dvali (ADD) (56) have proposed an alternative explanation for the weakness of gravity that has stimulated much theoretical and experimental work (see reviews in (15, 86, 87, 88, 89, 90)). Arkani-Hamed et al. conjecture that gravity is weak, not because the fundamental scale is high but because gravity can propagate in new dimensions less than a millimeter in size. Such “large” new dimensions are not seen by the standard-model particles because these are confined to a three-dimensional subspace of the higher-dimensional theory. Such a framework can be accommodated in string theory (57). A type of  $p$ -brane known as a D $p$ -brane does have gauge and other degrees of freedom as light excitations that are confined to the brane. If the standard-model particles are all confined to such a D3-brane, we will not sense additional dimensions except via their modification of the gravitational force law.

The hierarchy problem can be reformulated in this framework. One can assume that the fundamental scale  $M_*$  is of order 1 TeV (58). There is then no hierarchy

between the weak scale and  $M_*$  and no gauge-hierarchy problem. If there are  $n$  new dimensions, the higher-dimensional Newton's constant  $G_{(4+n)}$  can be taken to be

$$G_{(4+n)} = \frac{4\pi}{S_{(2+n)}} \left( \frac{\hbar}{M_* c} \right)^{(2+n)} \frac{c^3}{\hbar}, \quad (4)$$

where  $S_{(2+n)}$  is the area of a unit  $(2+n)$ -sphere,

$$S_{(2+n)} = \frac{2\pi^{(n+1)/2}}{\Gamma\left(\frac{n+1}{2}\right)}. \quad (5)$$

At sufficiently short distances, the gravitational force at a separation  $r$  would be proportional to  $G_{(4+n)}/r^{2+n}$ . To reconcile this with the  $1/r^2$  force law observed at long distances, Arkani-Hamed et al. take the  $n$  new dimensions to be compact. At distances that are long compared with the compactification scale, the gravitational flux spreads out evenly over the new dimensions and is greatly diluted. Using Gauss's Law, one finds that for  $n$  new dimensions with radius  $R_*$ , compactified on a torus, the effective Newton's constant at long distances is

$$G = \frac{\hbar c}{M_*^2} \left[ \frac{\hbar}{M_* c} \right]^n \frac{1}{V_n}. \quad (6)$$

Here  $V_n$  is the volume of the  $n$ -torus,  $(2\pi R_*)^n$ . The relationship between  $R_*$  and  $M_*$  for other geometries may be found simply by using the appropriate formula for the volume.

The hierarchy problem is then transmuted into the problem of explaining the size of the new dimensions, which are much larger than the fundamental scale. There are several proposals for stable compactifications of new dimensions that are naturally exponentially large (59, 60, 61, 62, 63).

To test the ADD proposal directly, one should probe the ISL at a distance scale on the order of  $R_*$ . Compact new dimensions will appear as new Yukawa-type

forces, of range  $R_*$ , produced by the exchange of massive spin-2 particles called Kaluza-Klein (KK) gravitons (64, 65, 66). To see this, note that the components of the graviton momenta in the compact dimensions must be quantized. For instance, compactification of a flat fifth dimension on a circle of radius  $R$  would impose the condition on  $P_5$ , the fifth component of the graviton momentum,  $P_5 = j\hbar/R$ , where  $j$  is an integer. The dispersion relation for a massless particle in five Lorentz-invariant dimensions is

$$E^2 = \sum_{i=0}^3 c^2 P_i^2 + c^2 P_5^2 . \quad (7)$$

Comparing this with the four-dimensional massive dispersion relation

$$E^2 = \sum_{i=0}^3 c^2 P_i^2 + c^4 M^2 , \quad (8)$$

we see that the fifth component of the momentum appears as a four-dimensional mass term. A five-dimensional graviton thus appears as an infinite number of new massive spin-2 particles. For a flat new dimension compactified on a circle of radius  $R$ , the mass  $m_j$  of the  $j$ th KK mode is  $m_j = j\hbar/(Rc)$  with  $j = 1, 2, \dots$

In factorizable geometries (whose spacetimes are simply products of a four-dimensional spacetime with an independent  $n$ -dimensional compact space), the squared wave functions of the KK modes are uniform in the new dimensions. Low-energy effective-field theory analyses of the KK modes and their couplings (67, 68, 69, 70) show that higher-dimensional general coordinate invariance constrains this effective theory. Even at distances less than  $R$ , KK mode exchange will not violate the equivalence principle. The leading terms in an expansion in  $1/M_*$  contain a universal coupling of each graviton KK mode  $G_{\mu\nu}^j$  to the stress tensor of form

$$-\sqrt{\frac{8\pi}{M_P}} \sum_j G_{\mu\nu}^j T^{\mu\nu} , \quad (9)$$

that is, each KK mode simply couples to the stress tensor in the same manner as the graviton. To compute the correction to the ISL for nonrelativistic sources at long distances, it suffices to consider the correction to the potential from the exchange of the lightest KK gravitons. The propagators for the KK states may be found in References (67, 68, 69, 70).

For  $n$  new dimensions compactified on a flat torus, with the same radius  $R_*$  for each dimension, the lowest-lying KK mode has multiplicity  $2n$  and Compton wavelength  $R_*$ . Direct searches for such new dimensions would observe such KK gravitons via the contribution of their lowest-lying modes to the Yukawa potential of Equation 2, giving  $\alpha = 8n/3$  and  $\lambda = R_*$ . A factor of  $4/3$  occurs in  $\alpha$  because a massive spin-2 particle has five polarization states, and the longitudinal mode does not decouple from a nonrelativistic source<sup>1</sup>. Other compact geometries will give similar effects, although the value of  $\alpha$  is quite model-dependent.

Assuming all new dimensions are compactified on a torus of radius  $R_*$ , and  $M_* = 1$  TeV, Equation 6 gives

$$R_* \approx \frac{1}{\pi} 10^{-17 + \frac{32}{n}} \text{ cm} .$$

The case  $n = 1$ ,  $R_* = 3 \times 10^{12}$  m, is clearly ruled out. The case  $n = 2$ ,  $R_* = 0.3$  mm, is inconsistent with the results of Reference (71). This case is even more strongly constrained by the observation of the neutrinos from supernova 1987A (72, 73, 74, 75, 76). Gravitational radiation into the extra dimensions would rapidly cool the supernova before the neutrinos could be emitted, imposing a con-

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<sup>1</sup>Note that References (81) and (82) included a contribution from a massless “radion” (gravitational scalar) in their Newtonian potential, and the radion KK modes in the Yukawa potential, leading to a different value for  $\alpha$ . We discuss the radion and why it should be massive later in this section.

straint  $R_* < 0.7 \mu\text{m}$ . The extra gravitational degrees of freedom also necessarily spoil the successful calculations of big-bang nucleosynthesis unless  $R_* < 2 \mu\text{m}$ , and the decay of the KK modes would add a diffuse background of cosmological gamma rays whose non-observation implies  $R_* < 0.05 \mu\text{m}$  (77). For  $n \geq 3$ ,  $R_*$  is less than about a nanometer, which is still allowed by astrophysics, cosmology, and direct searches.

It might, therefore, seem that direct observation of the new dimensions in ISL tests is out of the question. This conclusion is false. Astrophysical and cosmological bounds are still consistent with a single extra dimension of size 1 mm—in such a scenario the hierarchy problem might be solved via the existence of several more much smaller new dimensions (78). Furthermore, as discussed in the next section, it is easy to alter Equation 6 and the predictions for higher-dimensional graviton emission. Finally, there is a strong argument that the ADD proposal should modify the ISL at a scale of order  $\hbar M_P/(cM_*^2)$ .

In theories of gravity, the geometry of spacetime is dynamical and can fluctuate. In particular, the radius of new dimensions can fluctuate independently at each point in our four-dimensional spacetime. Thus, low-energy effective theories of compact extra dimensions inevitably contain spin-0 fields parameterizing the radii of the new dimensions. If the size of the new dimensions is not determined by dynamics, then the linear combination of these fields that determines the extra dimensional volume is a massless Brans-Dicke scalar (79) with gravitational strength coupling, known as the “radion.” A massless radion is decisively ruled out by tests of general relativity (80). Stabilization of the volume of the extra dimensions is equivalent to a massive radion. Since, with a low fundamental scale, the effective potential for the radion should not be much larger than  $\mathcal{O}(M_*^4)$ ,

and its couplings are proportional to  $G_N$ , the radion mass squared should be lighter than  $\mathcal{O}(G_N M_*^4)$ . The radion will mediate a new, gravitational strength force, with  $\alpha = n/(n+2)$  ((85); G. Giudice, R. Rattazzi, N. Kaloper, private communications). In many cases, the radion is the lightest state associated with new dimensions. For  $M_*$  less than a few TeV, its range should be longer than of order 100  $\mu\text{m}$ . Even for relatively “small” new dimensions, with size of order an inverse TeV, the radion will, under certain assumptions, have a Compton wavelength in the vicinity of 100  $\mu\text{m}$  (83, 84).

### 2.2.2 Warped extra dimensions

The previous discussion assumed the metric for the new dimensions is factorizable. However, the most general metric exhibiting four-dimensional Poincaré invariance is a “warped product,”

$$ds^2 = f(\xi_i) \eta_{\mu\nu} dx^\mu dx^\nu + g_{ij}(\xi_i) \xi_i \xi_j, \quad (10)$$

where the  $\xi_i$  are the coordinates of the new dimensions, and  $f$  and  $g$  are general functions of those coordinates. Solving the higher-dimensional Einstein equations for a spacetime with an embedded brane with nonvanishing tension typically requires warping. The “warp factor”  $f(\xi_i)$  may be thought of as a  $\xi$ -dependent gravitational redshift factor that leads to a potential term in the graviton wave equation. This potential can have a dramatic effect on the  $\xi$  dependence of the wave functions of the graviton, the graviton KK modes, and the radion.

Randall & Sundrum (91) (RS-I) noted that a large hierarchy can be obtained with a single small new dimension if the metric takes the form

$$ds^2 = e^{-2kr_c\xi} \eta_{\mu\nu} dx^\mu dx^\nu + r_c^2 d\xi^2, \quad (11)$$

where  $\xi$  is a coordinate living on the interval  $[0, \pi]$ ,  $k$  is a constant, and  $r_c$  is the compactification scale. This is just the metric for a slice of five-dimensional anti-deSitter space (maximally symmetric spacetime with constant negative curvature). It is also a solution to the five-dimensional Einstein equations with five-dimensional Newton's constant  $1/M_*^3$  if there is a negative cosmological constant of size  $\Lambda = -24M_*^3k^2$ , and if 3-branes are located at  $\xi = 0$  and  $\xi = \pi$  with tensions  $\pm 24M_*^3k$ . A negative-tension brane seems unphysical, but such bizarre objects can be constructed in string theory, provided the spaces on each side of the brane are identified with each other, that is, the brane represents a boundary condition on the edge of space. For large  $kr_c$ , most of the extradimensional volume of this space is near the positive-tension brane at  $\xi = 0$ .

To study the long-distance behavior of gravity in such a spacetime, one examines the behavior of small fluctuations of this metric of the form

$$ds^2 = e^{-2kr_c\xi}[\eta_{\mu\nu} + h_{\mu\nu}(x)]dx^\mu dx^\nu + r_c^2 d\xi^2. \quad (12)$$

Here  $h_{\mu\nu}$  is the four-dimensional graviton. Plugging this metric into Einstein's equations and linearizing in  $h$ , one finds  $h$  is a zero mode, or massless solution to the equations of motion, whose wave function in the compact dimension simply follows the warp factor  $e^{-2kr_c\xi}$ . Thus, there is a massless four-dimensional graviton that is localized about the brane at  $\xi = 0$  and exponentially weakly coupled to matter on the brane at  $\xi = \pi$ . If we further hypothesize that the latter brane is where the standard model lives, the weakness of gravity is explained for a moderate value of  $kr_c \sim 12$ . Both  $k$  and  $r_c^{-1}$  can be of the same order of magnitude as the fundamental scale, and so there is no large hierarchy in the input parameters.

As in the ADD case, the RS-I model has a radion parameterizing the compactification scale. Goldberger & Wise (92) have shown that  $kr_c$  in the desired

range can naturally be stabilized without large dimensionless inputs if the theory contains a massive scalar that lives in the bulk and has source terms localized on the branes. The radion then acquires a large mass of order 100 GeV. The curvature in the extra dimension has a huge effect on the KK graviton spectrum and couplings. The lightest KK modes have masses in the TeV region and large wave functions near our brane, and therefore  $\mathcal{O}(1)$  couplings to ordinary matter. This model has unusual experimental signatures at colliders (15) but is not testable with feasible probes of the ISL.

The RS-I model teaches us that warping can have significant effects on the phenomenology of the new dimensions. The coupling strength and masses of both the KK modes and the radion can be altered, and the graviton can be localized, or bound to a brane. Furthermore, warping is a generic phenomenon that should also occur in the ADD scenario. Even a very small amount of warping can greatly alter the coupling of the zero-mode graviton to our brane, which makes this coupling either much stronger or much weaker than for the case of flat extra dimensions (93), altering the relation of Equation 6. Even in the case of  $M_* = 1$  TeV and  $n = 2$ , with a very small amount of warping, the masses of the lightest KK modes can be either higher or lower than the inverse-millimeter scale predicted by the unwarped case.

### 2.3 *Infinite-Volume Extra Dimensions*

In a second paper (94), Randall & Sundrum (RS-II) explored the phenomenology of a graviton zero mode that is localized about a 3-brane embedded in a noncompact, infinite extra dimension. They found that five-dimensional gravity persists at all distance scales, with no gap in the KK spectrum, but at long distances the

$1/r^2$  force, mediated by the zero mode bound to the brane, dominates, and the extra dimension can be unobservable at low energy. A simple model of this effect is given by the metric

$$ds^2 = e^{-2k|z|} \eta_{\mu\nu} dx^\mu dx^\nu + dz^2, \quad (13)$$

where  $z$ , the coordinate of the fifth dimension, is noncompact. This metric, which represents two slices of anti-deSitter space glued together at  $z = 0$ , also solves Einstein's equations, given a negative bulk cosmological constant  $-24M_*^3 k^2$ , and a single 3-brane at  $z = 0$  of positive tension  $24M^3 k$ . The total gravitational potential between two masses  $m_1$  and  $m_2$  separated by a distance  $r$  on the brane may be found by summing up the contributions of the bound-state mode and the continuum KK spectrum, which, for distance scales longer than  $1/k$ , gives

$$V(r) = G_N \frac{m_1 m_2}{r} \left( 1 + \frac{1}{r^2 k^2} \right) \quad (14)$$

with  $G_N = \hbar^2 k / M_*^3$ . The experimental upper bound on  $1/k$  from  $N = 3$  terms in Equation 3 has not been explicitly computed but should be similar to the bound on the radius of an extra dimension. Therefore  $M_*$  must be larger than about  $10^9$  GeV, and there is still a gauge hierarchy. With two or more infinite new dimensions, and a graviton confined to our 3-brane, it is possible to lower  $M_*$  to 1 TeV (95). In such a scenario, the weakness of gravity is due to the zero-mode graviton wave function spreading over the extra dimensions, as in the ADD proposal, but the width of the wave function is set by the curvature scale rather than by the size of the dimension. Empirically, the main distinction between such weak localization and a large new dimension is that there is no gap in the KK spectrum and the ISL is modified by additional power-law corrections rather than by new Yukawa forces.

The RS-I explanation of the weakness of gravity—we live on a brane, the graviton is confined to a different, parallel brane and its wave function here is small—can also be realized in infinite extra dimensions (95, 96). Lykken & Randall studied such a configuration with a single extra dimension and concluded that the weakness of gravity could be explained without input of any large dimensionless numbers. The chief test of their scenario would be strong emission of graviton KK modes at a TeV collider. The continuum of KK modes would modify the ISL, but their effect would only be significant for distances smaller than  $\sim 10$  fm.

## 2.4 Exchange Forces from Conjectured New Bosons

Even if new dimensions are absent or small, the ISL can be modified at accessible distance scales by the exchange of new spin-0 or spin-1 bosons; spin-0 bosons would mediate an attractive Yukawa force while spin-1 bosons give a repulsive modification. Here we review some general considerations that apply to new bosons, and motivations for considering their existence.

### 2.4.1 Scalars: general theoretical considerations

In order for a scalar particle,  $\phi$ , to exert a coherent force on matter, it must have a Yukawa coupling to electrons, to  $u$ ,  $d$ , or  $s$  quarks, to the square of the gluon field strength, or to higher-dimension operators such as certain four-quark operators. The candidates of lowest dimension are

$$\frac{m_e}{f} \phi \bar{e}e , \quad \frac{m_d}{f} \phi \bar{d}d , \quad \frac{m_u}{f} \phi \bar{u}u , \quad \frac{1}{f} \phi G_{\mu\nu}^a G^{a,\mu\nu} . \quad (15)$$

When embedded in the standard model, these all arise from dimension-5 operators, hence the common factor of  $1/f$ , where  $f$  has dimensions of mass. We

have assumed that all chiral-symmetry-breaking operators should be proportional to fermion masses. With this assumption, and with all of the above operators present, the gluon coupling will dominate the scalar coupling to matter. Because the matrix element of  $G^2$  in a nucleon is roughly the nucleon mass,  $M_N$ , such an interaction would lead to a Yukawa potential of the form given in Equation 2 with  $\lambda = \hbar/(m_\phi c)$ , where  $m_\phi$  is the scalar mass and  $\alpha \simeq M_P^2/(4\pi f^2)$ .

An interaction  $(\phi/f)G^2$  produces radiative corrections to  $m_\phi$ . In the standard model with cutoff  $\Lambda$ , one finds

$$\delta m_\phi \simeq \frac{\Lambda^2}{4\pi f} \lesssim m_\phi . \quad (16)$$

The inequality expresses the requirement of naturalness. For  $f = M_P$  and  $m_\phi = 2 \times 10^{-4}$  eV, corresponding to a Compton wavelength of 1 mm, naturalness implies  $\Lambda \lesssim 5$  TeV. This scale  $\Lambda$  approximately coincides with the scale at which naturalness of the electroweak-breaking sector demands new physics. A scalar coupled more weakly would correspond to a higher value for  $\Lambda$ .

#### 2.4.2 Forces from axion exchange

A major loophole in the above arguments is that the interactions between matter and a new scalar may not arise from any of the operators in Equation 15, but rather from nonperturbative QCD effects. This is the case for the pseudoscalar axion invented to explain why strong interactions conserve  $CP$  to high precision. A pseudoscalar particle would normally not produce a Yukawa force between unpolarized bodies, but instantons in the presence of  $CP$  violation induce a scalar Yukawa coupling of the axion to matter that melts away above  $\Lambda_{\text{QCD}}$ . The softness of that coupling makes the radiative correction to the axion mass insignificant. However, a  $CP$ -violating scalar axion Yukawa coupling to matter

scales roughly as  $m_u \bar{\Theta}_{\text{QCD}}/f_a \simeq \bar{\Theta}_{\text{QCD}}(m_u m_a)/(m_\pi f_\pi)$ , where  $m_u \lesssim 5$  MeV is the  $u$  quark mass, and  $\bar{\Theta}_{\text{QCD}} \lesssim 10^{-9}(97)$  is the strong  $CP$ -violating angle.

Thus, for an axion mass  $m_a = 10^{-4}$  eV, the scalar axion coupling is at most about  $10^{-4}$  times gravitational strength. ISL tests with unpolarized bodies probe the square of this coupling, so they are quite insensitive to the axion. On the other hand, monopole-dipole tests (98), which search for a  $CP$ -violating force between unpolarized and polarized bodies, are linear in the coupling and should be a more sensitive axion probe.

#### 2.4.3 Scalars: cosmological considerations

A light, weakly interacting particle cannot decay or annihilate within a Hubble time, so its relic energy abundance must be equal to or less than that of the observed dark matter. However, the cosmology of scalars presents an important difficulty. A natural potential for a scalar in an effective theory below a cutoff  $\Lambda$  has the form  $V \sim \Lambda^4 \hat{V}(\phi/f)$ , where  $\Lambda \approx \sqrt{m_\phi f}$ , and  $\hat{V}$  is an arbitrary function that is assumed to contain no large dimensionless numbers. If all scalar couplings are proportional to  $1/f$ , then the scalar lifetime is of order  $4\pi f^2/m_\phi^3$ , essentially stable. If at a temperature  $T \sim \Lambda$  the thermal average of the scalar potential energy is  $\langle V \rangle \sim T^4$ , then the scalar field would have a large expectation value,  $\phi \sim f$ . The infinite-wavelength component of this expectation value will be frozen until the Hubble scale is of order  $1/m_\phi$ , and will subsequently act like cold dark matter. Assuming the standard-model spectrum and standard cosmology for  $T < \Lambda$  (e.g., that the reheat temperature following inflation is above  $\Lambda$ ), then an initial scalar energy density of  $T^4$  at  $T = \Lambda$  implies a ratio today of the energy

in cold scalars to the energy in baryons of order

$$\frac{\rho_w}{\rho_B} \simeq 2 \times 10^8 \left( \frac{\Lambda}{M_N} \right) , \quad (17)$$

which is clearly unacceptable.

Cosmology with light scalars can be made acceptable by invoking a very late stage of inflation with Hubble constant  $H$  less than or approximately  $m_\phi$ . Then  $\phi$  rapidly evolves to the minimum of its potential. Once inflation ends, the universe must reheat to a temperature  $T_R$ . However, the minimum of the scalar potential at  $T_R$  does not coincide with the minimum today, due to the tadpole generated by the interactions of Equation 15 at finite temperature. One must therefore check that coherent scalar oscillations are not regenerated during the reheating process after inflation. If reheating causes the minimum of the potential to change suddenly, relative to the oscillation time (of order  $10^{-13}$  s), then regeneration of the scalar condensate can be significant. We are almost completely ignorant of both the late inflationary mechanism and the timescale for reheating  $t_R$ , but a rough bound on  $t_R$  may be estimated from the reheating temperature using the sudden inflaton-decay approximation

$$t_r \sim (2/3)H^{-1} \sim (2/3) \left( \frac{M_P}{T_R^2} \right) \left( \sqrt{\frac{90}{8\pi^3 g_*}} \right) . \quad (18)$$

For  $T_R \gtrsim 10$  MeV, which is necessary for standard big-bang nucleosynthesis,  $t_R \sim 3 \times 10^{-3}$  s. Much higher reheat temperatures might be necessary to generate the baryon-number asymmetry. For example, a reheat temperature of about 100 GeV corresponds to a reheat time of order  $t_R \sim 3 \times 10^{-11}$  s.

Provided this timescale is much longer than the scalar oscillation time  $\hbar/(m_\phi c^2)$ , the evolution of the minimum of the potential can take place adiabatically, injecting little energy into the coherent mode. The requirement of such a late stage

of inflation with acceptable reheating constrains theories of particle physics near the weak scale but does not rule out the existence of light scalars.

#### 2.4.4 Bosons from hidden supersymmetric sectors

As we discussed in Section 2, new physics is expected at the TeV scale. One candidate for this new physics is supersymmetry, which is expected in unified theories, and which can explain the gauge hierarchy. Unbroken supersymmetry predicts an unobserved degeneracy between fermions and bosons, so supersymmetry must be broken at a scale of 100 GeV or higher. The most popular scenario involves supersymmetry breaking at a scale of  $M_S \sim 10^{11}$  GeV in a “hidden” sector that couples to our visible world only via gravity and interactions of similar strength. The apparent scale of supersymmetry breaking in the visible world would then be of order  $M_S^2/M_P \sim 10^3$  GeV. In other scenarios, supersymmetry breaking is communicated to the visible world by the gauge forces of the standard model, and the supersymmetry-breaking scale is as low as  $M_S \sim 10^4$  GeV. The supersymmetry-breaking scale is linked to  $m_{3/2}$ , the mass of the gravitino (the spin- $\frac{3}{2}$  superpartner of the graviton), through the relation  $m_{3/2} = M_S^2/M_P$ . Well-motivated theoretical expectations for the gravitino mass range from 1 meV to  $10^4$  GeV. In some scenarios (99, 100, 125, 126), the gravitino mass may be linked with the size of the cosmological constant inferred from the supernova observations and should be about 1 meV.

If there are hidden sectors—particles coupled to the visible sector only via gravitational strength interactions—the apparent scale of supersymmetry breaking in those sectors would typically be of order  $m_{3/2}$ . Scalar particles from those sectors could naturally have a mass in the meV range and mediate gravitational

strength forces with a range of about  $100 \mu\text{m}$ .

Note that the severe cosmological problems typical of light weakly coupled scalars discussed in the previous section do not necessarily occur for a scalar that is part of a hidden sector exhibiting supersymmetry down to the meV scale. Such scalars might have a potential coming from  $\mathcal{O}(1)$  couplings to particles in the hidden sector, while maintaining a naturally small mass and gravitational-strength couplings to particles in the visible sector. These couplings will allow for the scalar field to relax to its minimum and for particle decay and annihilation.

#### 2.4.5 Forces from exchange of stringy bosons

Supersymmetric hidden sectors are ubiquitous in string theory. All known acceptable vacua of string theory are supersymmetric and contain a tremendous number of “moduli”—massless scalar fields whose expectation values set the parameters of the effective theory. These moduli are extremely weakly coupled, with couplings inversely proportional to the fundamental scale. In order to give these fields a mass, it is necessary to break supersymmetry; however, moduli necessarily couple weakly to the supersymmetry-breaking sector and, for a low supersymmetry-breaking scale, are expected to be extremely light. Current understanding is inadequate to predict the moduli masses, but a rough estimate suggests these should be of order  $m_{3/2}$  (101). The best way to look for moduli is therefore to test the ISL at submillimeter distance scales. The couplings of the moduli in any given vacuum are computable, and so there are definite predictions. The best-understood scalar is the dilaton, a modulus that determines the strength of the gauge couplings. Its couplings to ordinary matter can be determined and are nearly free of QCD uncertainties, so its discovery could provide a

genuine smoking gun for string theory (102).

#### 2.4.6 Forces from the exchange of weakly coupled vector bosons

A new repulsive Yukawa interaction would be a signal for the exchange of a massive spin-1 boson, presumably a gauge particle. In the ADD scenario, any gauge fields that propagate in the bulk of the new dimensions would have their couplings diluted by the same volume factor as the graviton and so would mediate a force with similar strength. Actually, since the gravitational force is also weakened by the smallness of the  $M_N$  relative to  $M_*$ , one would expect any such gauge forces to be stronger than gravity by a very large factor of  $(M_*/M_N)^2 \sim 10^6\text{--}10^8$ . This is acceptable if the range is substantially shorter than 1 mm (see Section 4.4.3). Gauge bosons could have a mass in an interesting range if the symmetry is broken via a scalar condensate on a brane. The resulting mass would be diluted by the bulk volume as well, and would naturally be in the range  $M_*/(VM_*^3) \sim M_*^2/M_P$ . For  $M_*$  of order a few TeV, the range would be about 100  $\mu\text{m}$  (72). If the symmetry breaking occurs on the brane we live on, the gauge-boson couplings to standard-model matter could be substantially suppressed (105).

Compactifications of string theory and other extradimensional theories often contain new massless spin-1 particles, known as graviphotons, that arise from components of the higher-dimensional graviton. These generally do not couple to ordinary light matter, but such bosons might acquire small masses and small, gravitational-strength couplings to ordinary matter, e.g., by mixing with other vector bosons (103, 104, 107, 108). Light spin-1 bosons do not suffer from the naturalness or cosmological difficulties of scalar particles, provided that they couple to conserved currents. However, spin-1 (and spin-0) boson exchange necessarily

“violates” the equivalence principle and the couplings of bosons with masses less than 1  $\mu\text{eV}$  are strongly constrained by the experiment of Reference (109).

### 2.5 Attempts to Solve the Cosmological-Constant Problem

Comprehensive reviews of the cosmological-constant problem and the many attempts to solve it are available (110, 111, 112, 31, 113). Recent theoretical activity on this topic has been intense but is still inconclusive. Here we simply mention a few of the interesting recent proposals that imply modifications of the ISL at *long* distances.

Beane (32) pointed out that in any local effective quantum field theory, naturalness would imply new gravitational physics at a distance scale of order 1 mm that would cut off shorter-distance contributions to the vacuum energy. Sundrum (33) has speculated about the sort of effective theory that might do this. Sundrum proposed that the graviton is an extended object, with size of order 1 mm, and has been exploring how to construct a natural and viable effective field theory from this picture (33, 114). It is still not clear how self-consistent this effective theory is, but it does have the great virtue of making a definite, testable experimental prediction—gravity should shut off below a distance scale of order 100  $\mu\text{m}$ .

Many people have attempted to use extra dimensions to explain the smallness of the cosmological constant, motivated by the alluring observation (115) that in higher-gravitational theories with branes, the four-dimensional vacuum energy or brane tension does not necessarily act as a source of four-dimensional gravity but can instead lead to curvature only in the new dimensions. So far no solved, consistent example actually yields a small cosmological constant in

the four-dimensional effective description without extreme fine tuning or other problematic features.

Theories with branes and noncompact new dimensions allow another surprising phenomenon known as quasilocalization of gravity (116, 117, 118, 119). In these theories, as in RS-II, long-distance gravity is higher-dimensional. However, there is no zero mode bound to our 3-brane. There is, instead, a metastable quasibound state that propagates four-dimensionally along the brane over times and distances that are short compared with some maximum scale. The ISL, and four-dimensional general relativity, will approximately apply from  $r_{\min}$  to  $r_{\max}$ , but not to arbitrarily long distances. The consistency of various theories of quasilocalization is still under debate and the theories themselves have been mutating rapidly.

The holographic principle insinuates that a local description of a gravitational theory must break down somehow, because there are not enough degrees of freedom to allow independent observables at different spacetime points. Several theorists have speculated that the breakdown of locality might even occur in a subtle way at astronomical or even longer distances, and that this might explain the size of the cosmological constant (120, 121, 122, 123, 124). In the Banks scenario (120, 123, 125, 126), supersymmetry ends up being broken at a scale of a few TeV by nonlocal effects due to the cosmological constant, leading to masses for the gravitino, dilaton, and other moduli of order 1 meV and deviations from the ISL at 100  $\mu\text{m}$ .

Many of the above ideas share the possibility that there is some scale  $r_{\max}$  beyond which Einstein gravity is modified. Modifying gravity at long distance allows a new approach to the cosmological constant. The observed acceleration

of the universe might be caused by a change in the behavior of gravity at the Hubble scale, instead of by dark energy (127). The fascinating prospect that the effective Newton's constant might be strongly scale-dependent at large distance scales (gravity as a "high-pass spatial filter") leads to a new view of the cosmological-constant problem. Conventionally, it is assumed that the vacuum energy gravitates so weakly because, for some mysterious reason, this energy is actually very small. But if the strength of gravity depends on the wavelength of the source, it becomes credible that the vacuum energy is indeed very large but that it gravitates weakly because it is very smooth. Ideas along these lines have been pursued (128, 129, 130).

References (131, 132, 133, 134, 135) present an intriguing assertion about theories of quasilocalization that may account for the acceleration of the universe. For any localized gravitational source, there exists a distance scale  $r_*$  beyond which the graviton will acquire an extra polarization state that couples to the source so that the strength of gravity changes. This scale  $r_*$  is a function of the gravitational radius of the source and  $r_{\max}$ ; it decreases for less massive gravitating objects. Dvali et al. (135) argue that ultraprecise measurements of the anomalous precession of the perihelion of planetary orbits can test models of quasilocalization that explain the cosmological acceleration. For instance, a 17-fold improvement in this measurement in the Earth-Moon system via lunar-laser ranging (LLR) would test a particular model in Reference (135).

### 3 EXPERIMENTAL CHALLENGES

#### 3.1 Signals

The dominant problem in testing gravitation at short length scales is the extreme weakness of gravity. This forces the experimenter to adopt designs that maximize the signal and minimize backgrounds and noise. For example, one could measure the force between spheres (136), between cylinders (137, 138), between a sphere and a plane (139, 140), or in planar geometry (71, 141). Clearly, at a given minimum separation, the signal from a short-range interaction, per unit test-body mass, is least for two spheres and greatest for two planes.

The Yukawa force between two spheres of radii  $r_1$  and  $r_2$  and masses  $m_1$  and  $m_2$ , whose centers are separated by  $s$ , is

$$F_Y = \alpha G m_1 m_2 \Phi\left(\frac{r_1}{\lambda}\right) \Phi\left(\frac{r_2}{\lambda}\right) \left(1 + \frac{s}{\lambda}\right) \frac{e^{-s/\lambda}}{s^2}, \quad (19)$$

where  $\Phi(x) = 3(x \cosh x - \sinh x)/x^3$ . For  $x \gg 1$ ,  $\Phi(x) \approx 3e^x/(2x^2)$ , whereas for  $x \ll 1$ ,  $\Phi(x) \approx 1$ . Therefore, for  $\lambda \ll r$ , the ratio of Yukawa to Newtonian forces for two spheres of radius  $r$  separated by a gap  $d$  is

$$\frac{F_Y}{F_N} \approx \alpha \frac{9}{2} \frac{\lambda^3}{r^3} \left(1 + \frac{d}{2r}\right) e^{-d/\lambda}. \quad (20)$$

The potential energy from a Yukawa interaction between a flat plate of area  $A_p$ , thickness  $t_p$ , and density  $\rho_p$  at distance  $d$  from an infinite plane of thickness  $t$  and density  $\rho$  is

$$V_Y = 2\pi\alpha G \rho_p \rho \lambda^3 A_p \left[1 - e^{-t_p/\lambda}\right] \left[1 - e^{-t/\lambda}\right] e^{-d/\lambda}, \quad (21)$$

if end effects are neglected. The corresponding force is

$$F_Y = 2\pi\alpha G \rho_p \rho \lambda^2 A_p \left[1 - e^{-t_p/\lambda}\right] \left[1 - e^{-t/\lambda}\right] e^{-d/\lambda}. \quad (22)$$

In this case, for  $\lambda$  much less than the thicknesses, the force ratio becomes

$$\frac{F_Y}{F_N} \approx \alpha \frac{\lambda^2}{t_p t} e^{-d/\lambda}. \quad (23)$$

The potential energy of a Yukawa interaction between a sphere of radius  $r$  and mass  $m$  above an infinite plane of thickness  $t$  and density  $\rho_p$  is

$$V_Y = \pi \alpha G m \rho \lambda^2 \Phi(r/\lambda) e^{-s/\lambda}, \quad (24)$$

where  $s$  is the distance from the center of the sphere to the plane. The corresponding force is  $F_Y = \pi \alpha G m \rho \lambda \Phi(r/\lambda) e^{-s/\lambda}$ . In this case, for  $\lambda \ll r$ , the force ratio becomes

$$\frac{F_Y}{F_N} \approx \alpha \frac{3}{4} \frac{\lambda^3}{r^2 t} e^{-d/\lambda}, \quad (25)$$

where  $d$  is the gap between the spherical surface and the plane.

### 3.2 Noise Considerations

Thermal noise in any oscillator sets a fundamental limit on the achievable statistical error of its amplitude. A single-mode torsion oscillator subject to both velocity and internal damping obeys the equation

$$\mathcal{T} = I \ddot{\theta} + b \dot{\theta} + \kappa(1 + i\phi)\theta, \quad (26)$$

where  $\mathcal{T}$  is the applied torque,  $I$  the rotational inertia,  $\theta$  the angular deflection of the oscillator, and  $\kappa$  the torsional spring constant of the suspension fiber. The velocity-damping coefficient  $b$  accounts for any losses due to viscous drag, eddy currents, etc., and the loss angle  $\phi$  accounts for internal friction of the suspension fiber. We compute the spectral density of thermal noise following Saulson's (150) treatment based on the fluctuation-dissipation theorem. The spectral density of torque noise power (per Hz) at frequency  $\omega$  is

$$\langle \mathcal{T}_{\text{th}}^2(\omega) \rangle = 4k_B T \Re(Z(\omega)), \quad (27)$$

where  $k_B$  is Boltzmann's constant,  $T$  the absolute temperature, and  $Z = T/\dot{\theta}$  the mechanical impedance.

First consider the familiar case of pure velocity damping ( $b > 0, \phi = 0$ ) where  $Z(\omega) = iI\omega + b + \kappa/(i\omega)$ . In this case, the spectral density of torque noise,

$$\langle \mathcal{T}_{\text{th}}^2(\omega) \rangle = 4k_B T \frac{I\omega_0}{Q} \quad (28)$$

( $\omega_0 = \sqrt{\kappa/I}$  is the free resonance frequency and  $Q = I\omega_0/b$  the quality factor of the oscillator), is independent of frequency. The corresponding spectral density of angular-deflection noise in  $\theta$  is

$$\langle \theta_{\text{th}}^2(\omega) \rangle = \frac{4k_B T}{QI} \frac{\omega_0}{(\omega_0^2 - \omega^2)^2 + (\omega_0\omega/Q)^2}. \quad (29)$$

Note that the integral of Equation 29 over all  $f = \omega/(2\pi)$  is  $k_B T/\kappa$ , consistent with the equipartition theorem. The signal due to an external torque  $\mathcal{T}$  is

$$|\theta(\omega)| = \frac{\mathcal{T}}{I} \frac{1}{\sqrt{(\omega_0^2 - \omega^2)^2 + (\omega\omega_0/Q)^2}}, \quad (30)$$

so the signal-to-noise ratio in unit bandwidth has the form

$$S(\omega) = \frac{|\theta(\omega)|}{\sqrt{\langle \theta_{\text{th}}^2 + \theta_{\text{ro}}^2 \rangle}} = \frac{\mathcal{T}}{\sqrt{4k_B T \omega_0 I/Q + \langle \theta_{\text{ro}}^2 \rangle I^2 ((\omega_0^2 - \omega^2)^2 + (\omega\omega_0/Q)^2)}}, \quad (31)$$

where we have included a noise contribution  $\langle \theta_{\text{ro}}^2 \rangle$  from the angular-deflection readout system. The signal is usually placed at a frequency  $\omega \leq \omega_0$  to avoid attenuating the deflection amplitude  $\theta$  because of oscillator inertia.

Now consider the case of pure internal damping ( $b = 0, \phi > 0$ ) where  $Z = iI\omega + \kappa/(i\omega) + \kappa\phi/\omega$ . In this case, the spectral density of thermal noise has a  $1/f$  character,

$$\langle \mathcal{T}_{\text{th}}^2(\omega) \rangle = 4k_B T \frac{I\omega_0^2}{\omega Q}, \quad (32)$$

where now  $Q = 1/\phi$ . The corresponding spectral density of thermal noise in the

angular deflection is

$$\langle \theta_{\text{th}}^2 \rangle = \frac{4k_b T}{Q\omega I} \frac{\omega_0^2}{(\omega_0^2 - \omega^2)^2 + (\omega_0^2/Q)^2}. \quad (33)$$

The signal-to-noise ratio in unit bandwidth is

$$S = \frac{T}{\sqrt{4k_B T I \omega_0^2 / (Q\omega) + \langle \theta_{\text{ro}}^2 \rangle I^2 ((\omega_0^2 - \omega^2)^2 + (\omega_0^2/Q)^2)}}, \quad (34)$$

so it is advantageous to boost the signal frequency above  $\omega_0$  until  $\theta_{\text{ro}}^2$  makes a significant contribution to the noise.

### 3.3 Backgrounds

Electromagnetic interactions between the test bodies are the primary source of background signals and may easily dominate the feeble gravitational signal. In the following sections, we discuss the dominant electromagnetic background effects in ISL experiments.

#### 3.3.1 Electric potential differences and patch fields

Electric charges residing on insulating or ungrounded test bodies are difficult to quantify, and Coulomb forces acting on such bodies can exceed their weights. For this reason, ISL tests typically employ conducting grounded test bodies. Even so, a variety of effects can give the test bodies different electric potentials. If dissimilar materials are used for the test bodies, a potential difference equal to the difference between the work functions of the two materials is present, typically of order 1 V. Even if the same material is used for both test bodies or the test bodies are both coated with the same material, such as gold, small differences in the contact potentials connecting the test bodies to ground can leave a net potential difference between the test bodies. With care, such contact potential

differences can be reduced to the level of a few mV (142)).

Neglecting edge effects, the attractive electric force between a conducting plate with area  $A$  parallel to an infinite conducting plate is  $F_E(d) = \epsilon_0 AV^2/(2d^2)$ , where  $d$  is the separation between the plates,  $V$  is the potential difference between the plates, and  $\epsilon_0$  is the permittivity of free space. For 1-mm-thick plates with a density of 10 g/cm<sup>3</sup>, separated by 0.1 mm,  $F_E$  becomes as large as  $F_N$  for a potential difference of 10 mV, and the electric force grows with decreasing separation whereas the Newtonian force is constant.

Even if test bodies are at the same average potential, they experience a residual electric interaction from patch fields—spatially varying microscopic electric potentials found on the surface of materials (143). Patch fields arise because different crystal planes of a given material have, in general, work functions (144) that can in extreme cases differ by as much as 1 V. To the extent that the surface is a mosaic of random microscopic crystal planes, local potential differences will occur with a scale size comparable to the size of the microcrystals. For example, the work functions of different planes of W crystals differ by 0.75 V. Gold is a good choice for test-body coating because the work functions of its crystal planes vary by only 0.16 V. Surface contaminants also contribute to the local variation of the electric potential, altering the local work function and providing sites for the trapping of electrical charge. In the limit that the patches are smaller than the separation, the patch field force (143) scales as  $1/d^2$ .

### 3.3.2 Casimir Force

Vacuum fluctuations of the electromagnetic field produce a fundamental background to ISL tests at short length scales. The Casimir force (145) between

objects in close proximity may be viewed as arising either from the modification of the boundary conditions for zero-point electromagnetic modes or from the force between fluctuating atomic dipoles induced by the zero-point fields (146). The Casimir force can be quite large compared to the force of gravity. The Casimir force between two grounded, perfectly conducting, smooth, infinite planes at zero temperature, separated by a distance  $d$ , is attractive with a magnitude of

$$\frac{F_C}{A} = \frac{\pi^2 \hbar c}{240 d^4}. \quad (35)$$

For a 1-mm-thick plate of area  $A$  near an infinite plate of thickness 1 mm (again, both with density 10 g/cm<sup>3</sup>),  $F_C$  becomes equal to  $F_N$  at a separation of  $d = 13 \mu\text{m}$ .

Because precisely aligning two parallel planes is so difficult, experimenters usually measure the force between a sphere (or spherical lens) and a plane. Assuming perfectly conducting, smooth bodies at zero temperature, the Casimir force is attractive with a magnitude of

$$F_C = \frac{\pi^3 R \hbar c}{360 d^3}, \quad (36)$$

where  $R$  is the radius of the sphere and  $d$  is the minimum separation between the surfaces of the sphere and plane. For a 1-mm-radius sphere near an infinite 1-mm-thick plane (both with a density of 10 g/cm<sup>3</sup>),  $F_C$  becomes equal to  $F_N$  at a separation of  $d = 2.5 \mu\text{m}$ .

The Casimir-force expressions in Equations 35 and 36 must be corrected for finite temperature, finite conductivity, and surface roughness (see below). All these corrections vary with the separation,  $d$ , making it difficult to distinguish a gravitational anomaly from an electrical effect.

### 3.3.3 Electrostatic shielding

Fortunately, backgrounds from the Casimir force, electric potential differences, and patch-effect forces can be greatly reduced by using a moving attractor to modulate the signal on a stationary detector and placing a stationary, rigid, conducting membrane between the detector and the attractor. But this electrostatic shield places a practical lower limit of some tens of micrometers on the minimum attainable separation between the test bodies.

### 3.3.4 Magnetic effects

Microscopic particles of iron embedded in nominally nonmagnetic test bodies during their machining or handling, or in the bulk during smelting, can create local magnetic fields so small they are difficult to detect with standard magnetometers, yet large enough to compete with gravitational forces. The magnetic force between two magnetically saturated iron particles 1 mm apart, each 10  $\mu\text{m}$  in diameter, can be as large as  $10^{-7}$  dynes, varying as the inverse fourth power of the distance between the particles. This is as large as the gravitational attraction between a 1-mm-thick Al plate with an area of  $3 \text{ cm}^2$  near an infinite Al plate that is 1 mm thick. Yet the magnetic field of such a particle is only 0.3 mGauss at a distance of 2 mm.

Most ISL tests modulate the position of an attractor and detect the force this modulation produces on a detector. Even if the attractor has no ferromagnetic impurities, any magnetic field associated with the attractor modulation, e.g., from motor magnets or flowing currents, can couple to magnetic impurities in the detector. Experimenters typically measure the magnetic field associated with the modulation of the attractor and apply larger fields to find the response of the

detector. A variety of smaller magnetic background effects are associated with the magnetic susceptibilities of the test bodies. Standard magnetic shielding of the experimental apparatus is usually sufficient to reduce the ambient magnetic field to a level where the susceptibilities pose no problem.

### 3.3.5 Other effects

Modulation of the attractor position may introduce background effects that are not electromagnetic. The most obvious is a spurious mechanical coupling that transmits the motion of the attractor through the apparatus to the detector. These unwanted couplings can be reduced by multiple levels of vibration isolation and by experimental designs that force the signal frequency to differ from that of the attractor modulation. Experiments are performed in vacuum chambers to reduce coupling between the test bodies from background gas.

## 3.4 *Experimental Strategies*

ISL tests can be constructed as null experiments, partial-null experiments, or direct measurements. For example, Hoskins et al. (137) studied the force on a cylinder located inside a cylindrical shell. To the extent that the length-to-radius ratios of the cylinders are very large, this constitutes a null test because the Newtonian interaction between the cylinders gives no net force. Other null tests have used planar geometry; the Newtonian force between two parallel, infinite planes is independent of their separation. This basic idea, as discussed below, was exploited in Reference (141). An advantage of null experiments is that the apparatus does not need to handle signals with a wide dynamic range and the results are insensitive to instrumental nonlinearities and calibration uncertainties.

Hoyle et al. (71) have reported a partial-null experiment in which the Newtonian signal was largely, but not completely, cancelled. As discussed below, the partial cancellation greatly reduced the required dynamic range of the instrument, but Newtonian gravity still gave a very characteristic signal that was used to confirm that the instrument was performing properly. The form and magnitude of this signal provided constraints on new physics.

Finally, Mitrofanov & Ponomareva (136) reported a direct experiment that compared the measured force between two spheres as their separation was switched between two values. In this case, the results depended crucially on accurate measurement of the separations of the spheres and the forces between them.

## 4 EXPERIMENTAL RESULTS

### 4.1 *Low-Frequency Torsion Oscillators*

#### 4.1.1 The Washington experiment

Hoyle et al. (71) of the University of Washington Eöt-Wash group developed a “missing-mass” torsion balance (Figure 1), for testing the ISL at short ranges. The active component of the torsion pendulum was an aluminum ring with 10 equally spaced holes bored into it. The pendulum was suspended above a copper attractor disk containing 10 similar holes. The attractor was rotated uniformly by a geared-down stepper motor. The test bodies in this instrument were the “missing” masses of the two sets of 10 holes. In the absence of the holes, the disk’s gravity simply pulled directly down on the ring and did not exert a twist. But because of the holes, the ring experienced a torque that oscillated 10 times for every revolution of the disk—giving sinusoidal torques at  $10\omega$ ,  $20\omega$ , and  $30\omega$ ,

where  $\omega$  was the attractor rotation frequency. This torque twisted the pendulum/suspension fiber and was measured by an autocollimator that reflected a laser beam twice from a plane mirror mounted on the pendulum. Placing the signals at high multiples of the disturbance frequency (the attractor rotation frequency) reduced many potential systematic errors. A tightly stretched 20- $\mu\text{m}$ -thick beryllium-copper electrostatic shield was interposed between the pendulum and the attractor to minimize electrostatic and molecular torques. The entire torsion pendulum, including the mirrors, was coated with gold and enclosed in a gold-coated housing to minimize electrostatic effects. The pendulum could not “see” the rotating attractor except for gravitational or magnetic couplings. Magnetic couplings were minimized by machining the pendulum and attractor with nonmagnetic tools and by careful handling.

The experiment was turned into a partial-null measurement by adding a second, thicker copper disk immediately below the upper attractor disk. This disk also had 10 holes, but they were rotated azimuthally with respect to the upper holes by  $18^\circ$  and their sizes were chosen to give a  $10\omega$  torque that just cancelled the  $10\omega$  Newtonian torque from the upper attractor. On the other hand, a new short-range interaction would not be cancelled because the lower attractor disk was simply too far from the pendulum. The cancellation was exact for a separation (between the lower surface of the pendulum and the upper surface of the attractor) of about 2 mm. For smaller separations the contribution of the lower disk was too small to completely cancel the  $10\omega$  signal, and at larger separations the lower disk’s contribution was too large (see Figure 2).

Two slightly different instruments were used; both had 10-fold rotational symmetry and differed mainly in the dimensions of the holes. In the first experiment,

the pendulum ring was 2.002 mm thick with 9.545-mm-diameter holes and a total hole “mass” of 3.972 g; in the second experiment, the ring thickness was 2.979 mm with 6.375-mm-diameter holes having a total hole “mass” of 2.662 g. The resonant frequencies of the two pendulums,  $\omega_0/2\pi$ , were 2.50 mHz and 2.14 mHz, respectively; the fundamental  $10\omega$  signals were set at precisely  $\frac{10}{17}\omega_0$  and  $\frac{2}{3}\omega_0$ , respectively. In both cases, the  $20\omega$  and  $30\omega$  harmonics were above the resonance. The observed spectral density of deflection noise was close to the thermal value given in Equation 33 for the observed  $Q$  factor of 1500 (see also Figure 3 below).

#### 4.1.2 Signal scaling relations

The gravitational torque exerted on the pendulum by the rotating attractor is  $T_g(\phi) = -\partial V(\phi)/\partial\theta$ , where  $V(\phi)$  is the gravitational potential energy of the attractor when the attractor is at angle  $\phi$ , and  $\theta$  is the twist angle of the pendulum. For cylindrical holes, four of the six Newtonian torque integrals can be solved analytically but the remaining two must be evaluated numerically. Clearly, the Newtonian signal drops as the number of holes increases and their radii decrease because the long-range gravitational force tends to “average away” the holes. It also drops rapidly for separations much greater than the thickness of the upper attractor disk. Only three of the Yukawa torque integrals can be solved analytically. However, when the Yukawa range,  $\lambda$ , becomes much smaller than any of the relevant dimensions of the pendulum/attractor system, a simple scaling relation based on Equation 21 governs the signal and

$$T_Y \propto \alpha G \rho_p \rho_a \lambda^3 e^{-s/\lambda} \frac{\partial A}{\partial \phi}, \quad (37)$$

where  $\rho_p$  and  $\rho_a$  are the densities of the pendulum and attractor, respectively;  $\lambda$  is the Yukawa range; and  $A$  is the overlap area of the holes in the pendulum with

those of the attractor when the attractor angle is  $\phi$ .

#### 4.1.3 Backgrounds

Hoyle et al. (71) found that the effects from spurious gravitational couplings, temperature fluctuations, variations in the tilt of the apparatus, and magnetic couplings were negligible compared with the statistical errors. Electrostatic couplings were negligible because the pendulum was almost completely enclosed by a gold-coated housing. The 20- $\mu\text{m}$ -thick electrostatic shield was rigid to prevent secondary electrostatic couplings. The shield's lowest resonance was about 1 kHz, and the attractor could produce a false electrostatic effect only by flexing the shield at a very high  $m = 10$  mode.

#### 4.1.4 Alignment and calibration

Although all submillimeter tests of the ISL face an alignment problem, it was especially important in this experiment because of the relatively large size of the pendulum (chosen to increase the sensitivity). Alignment was done in stages. First the pendulum ring was leveled by nulling its differential capacitance as the pendulum rotated above two plates installed in place of the electrostatic shield. The shield was then replaced, and the tilt of the entire apparatus was adjusted to minimize the pendulum-to-shield capacitance. To achieve horizontal alignment, the gravitational torque was measured as the horizontal position of the upper fiber suspension point was varied. Determining separations from mechanical or electrical contacts gave unreliable results, so the crucial separation between the pendulum and the electrostatic shield was determined from the electrical capacitance.

The experimenters calculated the torque scale directly, using gravity. Two small aluminum spheres were placed in an opposing pair of the 10 holes of the torsion pendulum and two large bronze spheres, placed on an external turntable, were rotated uniformly around the instrument at a radius of 13.98 cm. Because this was close to the 16.76-cm radius (147) used in determining  $G$  and the ISL has been tested at this length scale (see Figure 4), the calibration torque could be computed to high accuracy. The torsion constant of the fiber was about 0.03 dyne cm.

#### 4.1.5 Results

Data were taken at pendulum/attractor separations down to 197  $\mu\text{m}$ , where the minimum separation was limited by pendulum “bounce” from seismic disturbances. The torque data, shown in Figure 2, were analyzed by fitting a potential of the form given in Equation 2 with  $\alpha$  and  $\lambda$  as free parameters and treating the important experimental parameters (hole masses and dimensions, zero of the separation scale, torque calibration constant, etc.) as adjustable parameters constrained by their independently measured values. Hoyle et al. reported results from the first of the two experiments in Reference (71); the combined 95%-confidence-level (CL) result of both experiments was given subsequently (148, 149) and is shown in Figure 5.

The results exclude the scenario of two equal extra dimensions whose size gives a unification scale of  $M^* = 1$  TeV; this would imply an effective Yukawa interaction with  $\lambda = 0.3$  mm and  $\alpha = 16/3$  if the extra dimensions are compactified as a torus. Because  $\alpha \geq 16/3$  is consistent with the data only for  $\lambda < 130$   $\mu\text{m}$ , Equation 6 implies that  $M_* > 1.7$  TeV. A tighter bound on  $M_*$  can be extracted

from the radion constraint, which, in the unwarped case where  $1/3 \leq \alpha \leq 3/4$  for  $1 \leq n \leq 6$ , suggests that  $M_* \geq \mathcal{O}(3 \text{ Tev})$ .

More interesting and general is the upper limit placed on the size of the largest single extra dimension, assuming all other extra dimensions are significantly smaller (71, 149). For toroidal compactification, this corresponds to the largest  $\lambda$  consistent with  $\alpha = 8/3$ , leading to an upper limit  $R_* \leq 155 \mu\text{m}$ . Other compactification schemes necessarily give somewhat different limits.

## 4.2 *High-Frequency Torsion Oscillators*

### 4.2.1 The Colorado experiment

The modern era of short-range ISL tests was initiated by Long et al. at the University of Colorado (151). Their apparatus, shown in Figure 6, used a planar null geometry. The attractor was a small  $35 \text{ mm} \times 7 \text{ mm} \times 0.305 \text{ mm}$  tungsten “diving board” that was driven vertically at 1 kHz in its second cantilever mode by a PZT (lead zirconate titanate) bimorph. The detector, situated below the diving board, was an unusual high-frequency compound torsion oscillator made from 0.195-mm-thick tungsten. It consisted of a double rectangle for which the fifth normal mode resonates at 1 kHz; in this mode, the smaller  $11.455 \text{ mm} \times 5.080 \text{ mm}$  rectangle (the detector) and the larger rectangle (one end of which was connected to a detector mount) counter-rotated about the torsional axis, with the detector rectangle having the larger amplitude. The torsion oscillations were read out capacitively from the larger rectangle. The attractor was positioned so that its front end was aligned with the back edge of the detector rectangle and a long edge of the attractor was aligned above the detector torsion axis. A small electrostatic shield consisting of a 0.06-mm-thick sapphire plate coated with 100

nm of gold was suspended between the attractor and the detector. The attractor, detector, and electrostatic shield were mounted on separate vibration-isolation stacks to minimize any mechanical couplings and were aligned by displacing the elements and measuring the points of mechanical contact.

In any null experiment, it is helpful to know the precise form of a signal of new physics. Long et al. slid away the electrostatic shield and applied a 1.5-V bias to the detector to give a large, attractive electrostatic force; this determined the phase of the signal that would be produced by a new, short-range interaction.

#### 4.2.2 Signal-to-noise considerations and calibration

The spectral density of thermal-force noise in the multimode oscillator used in Reference (151) obeys a relation similar to Equation 32. The Colorado experimenters operated on a resonance with a  $Q = 25,000$  so the readout noise was negligible. Data were taken with the attractor driven at the detector resonance as well as about 2 Hz below the resonance (see Figure 7). The mean values of the on-resonance and off-resonance data agreed within errors, but the standard deviation of the on-resonance data was about twice that of the off-resonance data. This is just what one would expect if the on-resonance data were dominated by thermal noise. Furthermore, the on-resonance signal did not change as the geometry was varied. This ruled out the unlikely possibility that the observed null result came from a fortuitous cancellation of different effects, all of which should have different dependences on the geometry. The torsion oscillation scale was calibrated by assuming that the on-resonance signal was predominantly thermal.

#### 4.2.3 Backgrounds

Although a net signal was seen, it had the same magnitude on and off resonance and presumably was due to electronic pickup. No evidence was seen for an additional, statistically significant background. Checks with exaggerated electrostatic and magnetic effects showed that plausible electrostatic and magnetic couplings were well below the level of thermal noise.

#### 4.2.4 Results

The null results from this experiment, taken at a separation of  $108 \mu\text{m}$ , were turned into  $\alpha(\lambda)$  constraints using a maximum-likelihood technique. For various assumed values of  $\lambda$ , the expected Yukawa force was calculated numerically 400 times, each calculation using different values for experimental parameters that were allowed to vary within their measured ranges. A likelihood function constructed from these calculations was used to extract 95%-CL limits on  $\alpha(\lambda)$ . The results (141), shown in Figure 5, exclude a significant portion of the moduli forces predicted by Dimopoulos & Giudice (101).

### 4.3 Microcantilevers

#### 4.3.1 The Stanford experiment

Chiaverini et al. at Stanford (152, 153) recently reported a test of the ISL using the microcantilever apparatus shown schematically in Figure 8. This instrument was suited for the  $10\text{-}\mu\text{m}$  length scale but lacked the sensitivity to see gravity. The apparatus consisted of a silicon microcantilever with a  $50 \mu\text{m} \times 50 \mu\text{m} \times 50 \mu\text{m}$  gold test mass mounted on its free end. The cantilever had a spring constant of about 5 dyne/cm, and its displacement was read out with an optical-fiber inter-

ferometer. The microcantilever, which hung from a two-stage vibration-isolation system, oscillated vertically in its lowest flexural mode at a resonant frequency of  $\omega_0 \approx 300$  Hz. The microcantilever was mounted above an attractor consisting of five pairs of alternating  $100 \mu\text{m} \times 100 \mu\text{m} \times 1 \text{ mm}$  bars of gold and silicon. The attractor was oscillated horizontally underneath the cantilever at about 100 Hz by a bimorph; the amplitude was chosen to effectively resonantly excite the cantilever at the third harmonic of the attractor drive frequency. The geometry was quite complicated; the third harmonic gravitational force on the cantilever depended sensitively and nonlinearly on the drive amplitude. An electrostatic shield consisting of a  $3.0\text{-}\mu\text{m}$ -thick silicon nitride plate with 200 nm of gold evaporated onto each side was placed between the cantilever and the attractor. Data were taken with the vertical separations between the cantilever and the attractor as small as  $25 \mu\text{m}$ .

#### 4.3.2 Signal-to-noise considerations

The dominant noise source in the Stanford experiment was thermal noise in the cantilever, which was reduced by operating at about 10 K. The  $Q$  factors of the oscillating cantilevers in these measurements were typically about 1200.

#### 4.3.3 Calibration and alignment

The cantilever spring constant  $k$  was found in two independent ways that agreed to within 10%: by assuming that when the cantilever was far from the attractor it was in thermal equilibrium with its surroundings, and by calculating  $k$  from the measured resonant frequency. The cantilever was aligned with respect to the attractor using magnetic forces. The cantilever's test mass had a thin nickel film

on one face, and the attractor was equipped with a zig-zag conducting path that followed the gold bars. When a current was run through the attractor, it placed a force on the cantilever that had half the frequency and phase of the expected gravitational signal but vastly greater amplitude. This force was used to align the apparatus.

#### 4.3.4 Backgrounds

This experiment was limited by a spurious force about 10 times greater than the thermal detection limit. This force was clearly not fundamental, i.e., related to the mass distributions on the attractor, because the phase of signal did not behave as expected when the horizontal offset of the attractor oscillation was varied or as the attractor drive amplitude was changed. The most likely source of a spurious force is electrostatics; the cantilever was not metallized and so it could hold charge and the shield was observed to vibrate by a picometer or so. A potential on the cantilever of about 1 V would be sufficient to produce the observed force. Although thin nickel layers were incorporated into the test mass and attractor, the experimenters estimate that magnetic forces from the nickel (as well as from iron impurities in the gold) were too small to explain the observed background force. Vibrational coupling between the attractor and cantilever was minimized because the attractor was moved at right angles to the cantilever's flex.

#### 4.3.5 Results

The experimenters saw a spurious  $(8.4 \pm 1.4) \times 10^{-12}$  dyne force when the attractor and cantilever were at their closest separation of  $25\mu\text{m}$ . They assigned a 95%-CL

upper limit on a Yukawa interaction by computing the minimum  $\alpha$  as a function of  $\lambda$  that would correspond to this central value plus two standard deviations. Figure 9 shows their constraint, which rules out much of the parameter space expected from moduli exchange as computed in Reference (101).

#### 4.4 *Casimir Force Experiments*

Early attempts to detect the Casimir force between metal surfaces (154) and dielectric surfaces (155, 156, 157, 158) had relatively large errors. Nonetheless, it was recognized (159, 160, 161) that such measurements provided the tightest constraints on new hypothetical particles with Compton wavelengths less than 0.1 mm. In recent years, three groups have reported measurements of the Casimir force with relative errors of 1% to 5%. Although these experiments are orders of magnitude away from providing tests of the ISL, they do probe length scales from 20 nm to 10  $\mu\text{m}$ , where large effects may occur (see Section 2.4.4).

##### 4.4.1 Experimental methods

The first of the recent experiments, performed by Lamoreaux at the University of Washington (139, 162), used a torsion balance to measure the force between a flat quartz plate and a spherical lens with a radius of  $12.5 \pm 0.3$  cm. Both surfaces were coated with 0.5  $\mu\text{m}$  of copper followed by 0.5  $\mu\text{m}$  of gold. A piezoelectric stack stepped the separation between the plate and lens from 12.3  $\mu\text{m}$  to 0.6  $\mu\text{m}$ , at which point the servo system that held the torsion pendulum angle constant became unstable. The force scale was calibrated to 1% accuracy by measuring the servo response when a 300-mV potential difference was applied between the plate and lens at a large ( $\approx 10 \mu\text{m}$ ) separation. The absolute separation between

the lens and plate was obtained by applying a potential difference between the two surfaces and fitting the measured force (for distances greater than 2  $\mu\text{m}$  where the Casimir force was small) to the expected  $1/d$  dependence, where  $d$  is the distance between the plate and lens. After subtracting the  $1/d$  component from the force scans, the residual signals were fitted to the expected form for a Casimir force, and they agreed to within 5% (139, 162).

Mohideen and collaborators at the University of California at Riverside reported a series of experiments that used an atomic-force microscope (AFM) to measure the Casimir force between a small sphere and a flat plate (140, 163, 164, 165). Their most recent measurement used a 191- $\mu\text{m}$ -diameter polystyrene sphere that was glued to a 320- $\mu\text{m}$ -long AFM cantilever. The cantilever plus sphere and a 1-cm-diameter optically polished sapphire disk were coated with 87 nm of gold, with a measured surface roughness of  $1.0 \pm 0.1 \text{ nm}$ . The disk was placed on a piezoelectric tube with the sphere mounted above it, as shown in Figure 10. The cantilever flex was measured by reflecting laser light from the cantilever onto split photodiodes. The force scale was calibrated electrostatically by applying a  $\pm 3\text{-V}$  potential difference between the sphere and disk at a separation of 3  $\mu\text{m}$ . The force difference between the +3 V and -3 V applied potentials was used to determine the residual potential difference between the disk and sphere when their external leads were grounded together:  $3 \pm 3 \text{ mV}$ . The force between the sphere and disk was measured for separations ranging from 400 nm to contact. It was found that the surfaces touched when their average separation was  $32.7 \pm 0.8 \text{ nm}$ . This was attributed to gold crystals protruding from the surfaces. The measured forces were compared to the expected Casimir force for separations of 62–350 nm and agreement to within 1% was found (165).

The record for measuring the Casimir force at the closest separation is held by Ederth (166) at the Royal Institute of Technology in Stockholm, who measured the force between crossed cylindrical silica disks with diameters of 20 mm. A template-stripping method (167) was used to glue 200-nm layers of gold, with an rms surface roughness of  $\leq 0.4$  nm, to the silica disks. The gold surfaces were then coated with a 2.1-nm-thick layer of hydrocarbon chains to prevent the adsorption of surface contaminants and the cold-welding of the gold surfaces upon contact. One cylindrical surface was attached to a piezoelectric stack and the other to a piezoelectric bimorph deflection sensor that acted as a cantilever spring. The two surfaces were moved toward one another starting at a separation  $> 1 \mu\text{m}$ , where the Casimir force was less than the resolution of the force sensor, and ending at a separation of 20 nm, at which point the gradient of the Casimir force was comparable to the stiffness of the bimorph spring, causing the surfaces to jump into contact. The stiffness of the bimorph sensor was calibrated by continuing to move the piezotube another 200–300 nm while the surfaces were in contact. The absolute separation between the surfaces was found by fitting the measured force curve to the expected Casimir signal (plus electrostatic background, which was found to be negligible) with the absolute separation as a fit parameter. At contact, the surfaces compressed by  $\approx 10$  nm. The measured force was compared to the expected Casimir force over the range of separations from 20 to 100 nm and an agreement to better than 1% was found.

#### 4.4.2 Signal-to-noise and background considerations

The signal-to-noise ratio for Casimir-force measurements as tests of the ISL may be improved by using more sensitive force probes, using thicker metallic coat-

ings on the test bodies, and operating at lower temperatures. Nonetheless, the dominant limitation for interpreting the measurements as tests of the ISL is understanding the Casimir-force background to high accuracy. There is a growing literature on the corrections that must be applied to the Casimir force calculated for smooth, perfect conductors at zero temperature (Equations 35 and 36). The dominant corrections are for finite temperature, finite conductivity, and surface roughness. Corrections for finite temperature are important for test-body separations  $d > 1 \mu\text{m}$ . For the Lamoreaux experiment, the finite-temperature corrections at 1- $\mu\text{m}$  and 6- $\mu\text{m}$  separations were 2.7% and 174% of the zero-temperature Casimir force, respectively (168). A number of authors have considered the effects of finite conductivity on the temperature correction (169, 170, 171), and results believed to be accurate to better than 1% were obtained. The correction to the Casimir force for the finite conductivity of the metallic surfaces is of order 10% at  $d = 1 \mu\text{m}$  and grows with smaller separations. Finite-conductivity corrections using a plasma model for the dielectric function of the metal give the correction as a power series in  $\lambda_P/d$ , where  $\lambda_P$  is the plasma wavelength of the metal (172, 173, 174). Corrections have also been obtained using optical data for the complex dielectric function (175, 165, 176, 177). Surface roughness of the test bodies contributes a correction to the Casimir force that can be expressed as a power series in  $h/d$ , where  $h$  is a characteristic amplitude of the surface distortion (178, 179, 180, 174). For stochastic distortions, the leading-order surface-roughness correction is  $6(h/d)^2$ , which is less than 1% of the Casimir force at closest separation in the experiments of Ederth and the Riverside group.

#### 4.4.3 Results

Constraints on Yukawa interactions with ranges between 1 nm and 10 $\mu$ m, shown in Figure 9, have been extracted from the Casimir-force measurements of Lamoreaux (168, 151), Ederth (181), and the Riverside group (182, 183, 7, 184). Figure 9 also shows constraints at even smaller ranges obtained from earlier van der Waals-force experiments (185). It should be noted that most of these constraints were obtained by assuming that a Yukawa force could not exceed the difference between the measured force and the predicted Casimir effect. To be rigorous, the raw data should be fitted simultaneously with both Casimir and Yukawa forces, which should lead to significantly less stringent limits on  $|\alpha|$ . Deviations from Newtonian gravity in this region that follow a power law (Equation 3) are constrained more strongly by the much more sensitive longer-range gravity experiments discussed above (7).

#### 4.5 *Astronomical Tests*

A summary of constraints on Yukawa interactions with  $\lambda \geq 1$  mm may be found in Figure 2.13 of the 1999 review by Fischbach & Talmadge (14), which we reproduce in part in our Figure 4. Since the publication of Reference (14), the constraints for  $\lambda \leq 1$  cm have been substantially improved, as discussed above. The constraints at larger ranges from laboratory, geophysical, and astronomical data (see Figure 4) are essentially unchanged. The astronomical tests provide the tightest constraints on  $\alpha$ . These are typically based on Keplerian tests comparing  $G(r)M_{\odot}$  values deduced for different planets. However, the tightest constraint comes from lunar-laser-ranging (LLR) studies of the lunar orbit. Because this result may improve significantly in the next few years, we give some details of

the measurement here.

The LLR data consist of range measurements from telescopes on Earth to retroreflectors placed on the Moon by US astronauts and an unmanned Soviet lander. The measurements, which began in 1969, now have individual raw range precisions of about 2 cm and are obtained from single photon returns, one of which is detected for roughly every 100 launched laser pulses (186). The vast majority of the data come from sites in Texas (187) and in southern France (188). The launched laser pulses have full widths at half maximum of about 100 ps; the return pulses are broadened to about 400 ps because the reflector arrays typically do not point straight back to Earth owing to lunar librations. The launch-telescope-to-lunar-retroreflector ranges have to be corrected for atmospheric delay, which is computed from the local barometric pressure, temperature, and humidity. For the Moon straight overhead, the range correction at the Texas site is about 2 m. The dominant uncertainties in converting raw range measurements into separations between the centers of mass of the Earth and the Moon come from tidal distortions of the Earth and Moon and atmospheric and ocean loading of the Earth. The current model, using the entire world data set, gives an uncertainty of about 0.4 cm in the important orbit parameters.

The most sensitive observable for testing the ISL is the anomalous precession of the lunar orbit. If the Moon were subject only to a central Newtonian  $1/r$  potential from the Earth, the lunar orbit would not precess. The orbit does precess due to the Earth's quadrupole field and perturbations from other solar-system bodies, as well as from the small general relativistic geodetic precession and possibly also from a Yukawa interaction; the conventional sources of precession must be accounted for to obtain the anomalous Yukawa precession rate. Ignoring terms

of order  $\varepsilon^2$ , where the Moon's eccentricity is  $\varepsilon = 0.0549$ , the anomalous Yukawa precession rate  $\delta\omega$  is (14)

$$\frac{\delta\omega}{\omega} = \frac{\alpha}{2} \left( \frac{a}{\lambda} \right)^2 e^{-a/\lambda}, \quad (38)$$

where  $\omega = 2\pi$  radians/month and  $a$  is the mean radius of the Moon's orbit. The constraint on  $\alpha(\lambda)$  is tightest for  $\lambda = a/2$  and falls off relatively steeply on either side of  $\lambda = a/2$ . The current LLR  $2\sigma$  upper limit on  $\delta\omega$  is  $270 \mu\text{as}/\text{y}$ ; this follows because the observed precession of about 19.2 mas/y agrees with the general relativistic prediction to  $(-0.26 \pm 0.70)\%$ , where the error is “realistic” rather than “formal” (the error quoted in Reference (189) should be doubled; J. Williams, private communication 2003). We conclude that at 95% CL,  $\delta\omega/\omega < 1.6 \times 10^{-11}$ ; the corresponding LLR constraint is shown in Figure 4.

## 5 CONCLUSIONS

### 5.1 *Summary of Experimental Results*

Because gravity is intimately connected to the geometry of spacetime, ISL tests could provide very direct evidence for the existence of extra space dimensions. In addition, ISL tests are sensitive to the exchange of proposed new low-mass bosons. A variety of theoretical considerations hint that new effects may occur at length scales between  $10 \mu\text{m}$  and  $1 \text{ mm}$ . This circumstance, as well as the urge to explore unmapped territory, has motivated the development of new experimental techniques that have produced substantial improvements in constraints on theories. The overall slope of the experimental constraints shown in Figures 5, 9, and 4 reflects the rapidly decreasing signal strength of a new interaction as its range decreases. At gravitational strength ( $\alpha = 1$  in Figure 5), the

ISL has been verified down to a distance  $\lambda = 200 \mu\text{m}$ . At length scales between 20 nm and 4 mm, many square decades in Yukawa-parameter space have been ruled out. These results have eliminated some specific theoretical scenarios, but many other interesting ideas are still viable because their predicted effects lie somewhat below the current experimental limits.

## 5.2 Prospects for Improvements

### 5.2.1 Short-range tests of the ISL

To make a gravitational-strength ( $\alpha = 1$ ) ISL test at a 20- $\mu\text{m}$  length scale requires an increase in the background-free sensitivity of at least a factor of  $10^3$ . Fortunately, such an increase is possible, although it will require years of development.

The Eöt-Wash group are currently running a new apparatus that features a pendulum/attractor system having 22-fold rotational symmetry with 44 thinner, smaller-diameter holes. The pendulum ring and attractor disk are made from denser materials (copper and molybdenum, respectively). Noise has been improved by a factor of six. The closest attainable separation has been reduced by a factor of two by adding a passive “bounce”-mode damper to the fiber-suspension system, and the thickness of the electrostatic shield has been reduced to 10  $\mu\text{m}$ . Figure 3 shows the spectral density of the torque signal from this apparatus. This instrument should probe Yukawa forces with  $|\alpha| = 1$  for ranges down to  $\lambda = 60 \mu\text{m}$ . In principle, it is possible to use a low-frequency torsion balance in a different mode, one that measures the attraction between two flat plates (J.G. Gundlach, private communication). This would provide a null test with a sensitivity that scaled as  $\lambda^2 e^{-s/\lambda}$  rather than as  $\lambda^3 e^{-s/\lambda}$  in the partial-null

experiments.

The Colorado group plans to optimize their geometry and to use a Washington-style electrostatic shield to attain closer separations. This could improve their limits between 10  $\mu\text{m}$  and 50  $\mu\text{m}$  by at least an order of magnitude. In the long run, both groups could run at liquid-helium temperatures, which will give lower noise, not only from the decreased  $k_B T$  factor, but also from the expected increase in the  $Q$  factor of the torsion oscillator. Newman (190) found that the  $Q$  factor of a torsion fiber has two components. One is temperature-independent but amplitude-dependent (this is already negligible in the Eöt-Wash instrument because of the small amplitudes employed) and the other is temperature-dependent and amplitude-independent.

The microcantilever application exploited by the Stanford group has not yet attained its full potential. Presumably, lessons learned in this pioneering experiment will reduce the backgrounds and allow the experimenters to exploit their inherent sensitivity to new very small forces. Because corrections to the idealized Casimir force can be large and depend on properties of the test bodies that are troublesome to quantify, it may be difficult to compare Casimir-force experiments to theory at an accuracy much better than 1%. The finite-conductivity corrections depend on the dielectric properties of the actual metallic coating of the test bodies, which may differ somewhat from bulk dielectric properties used in the calculation. As the experimental precision improves, parameters associated with the conductivity correction (such as  $\lambda_P$ ) may need to be included as adjustable parameters in fitting the measured force-versus-distance curves. The surface-roughness correction should consider distortions over length scales larger than are easily accessible by AFM scans, and it may be necessary to vary the

roughness parameters as well. Both corrections scale as inverse powers of the separation,  $d$ , as do the corrections for residual electric potential and patch effects. Compounding the problem of multiple corrections with similar distance dependences is the uncertainty in the absolute separation of the test bodies. The Casimir force depends on  $d_0 + d_r$  rather than on  $d$ , where  $d_r$  is the relative displacement of the test bodies between force measurements (which can be accurately measured) and  $d_0$  is the absolute separation at the origin of the relative scale (which is difficult to determine accurately). Including  $d_0$  as a fit parameter allows other short-distance parameters to vary (166) without affecting the fit at large distances, where the fractional error on the force measurements is larger. It is unlikely that the next few years will bring large improvements in Yukawa constraints from Casimir-force experiments.

### 5.2.2 Long-range tests of the ISL

Because any change in orientation of the Moon’s ellipticity grows linearly with time, even with data of constant precision the LLR constraint should improve in proportion as the data span increases (assuming that the modeling of conventional precession sources is not a limiting factor). New LLR projects should improve the raw range precision by an order of magnitude, bringing the precision into the range needed to test the “high-pass” gravity model (6). For example, APOLLO (191) will exploit a 3.5-m telescope at an elevation of 2780 m and subarcsecond image quality. This instrument should receive several returned photons per laser shot, giving a data rate about  $10^3$  times greater than existing facilities. It is expected that more precise data will lead to corresponding improvements in the modeling.

Ranging to other planets is necessary in order to probe longer length scales effectively. This is currently done using radar (which is limited by the absence of a well-defined “target” on the planet) or else microwave signals transmitted by orbiting spacecraft (which are limited by uncertainties and the finite timespan of the orbits). Furthermore, the accuracy of microwave ranges is limited by propagation delay in the interplanetary solar plasma. It is impractical to laser-range to passive reflectors on other planets (if they could be placed) because the returned signal falls as  $1/r^4$ . However, recent developments in active laser transponders, whose sensitivity falls as  $1/r^2$ , make it practical to place such a device on Mars and ultimately achieve range precisions of a few centimeters (192). This would yield several interesting new gravitational measurements, including an improved test of the strong equivalence principle (193), which provides one of the best limits on massless gravitational scalar fields, as well as tests of the ISL that would give interesting constraints on the quasilocalized gravity model of Reference (128).

ISL tests at scales larger than the solar system typically rely on uncertain astrophysical models. But Will (5) notes that the proposed LISA space-based interferometer could test a pure Yukawa potential at a scale of  $5 \times 10^{19}$  m by studying distortions of the gravitational waveform from an inspiraling pair of  $10^6 M_\odot$  compact objects.

### 5.3 *What if a Violation of the $1/r^2$ Law Were Observed?*

Suppose that future experiments revealed a violation of the ISL at short length scales. Of course, one would try to tighten the constraints on its range and strength by performing tests using instruments with varying length scales. But

a new question immediately arises: Is the new physics a geometrical effect of extra dimensions or evidence for exchange of a new boson? This can be decided by testing whether the short-range interaction violates the equivalence principle: Boson exchange generically does not couple to matter in a universal manner and therefore appears as a “violation” of the equivalence principle, whereas geometrical effects must respect the principle. Kaplan & Wise (102) estimated that the equivalence-principle-“violating” effect from dilaton exchange is  $\approx 0.3\%$ .

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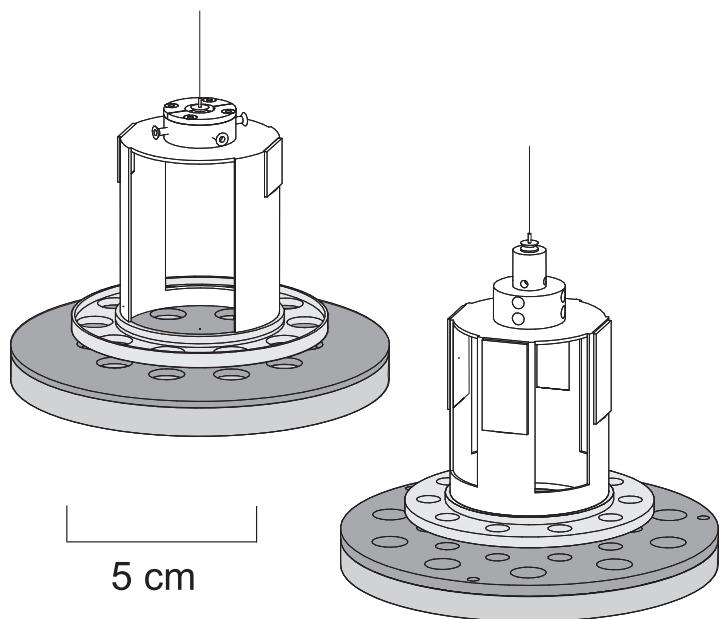


Figure 1: Schematic diagram of the 10-hole pendulums and rotating attractors used in the two experiments of Hoyle et al. (71, 148, 149). The active components are shaded.

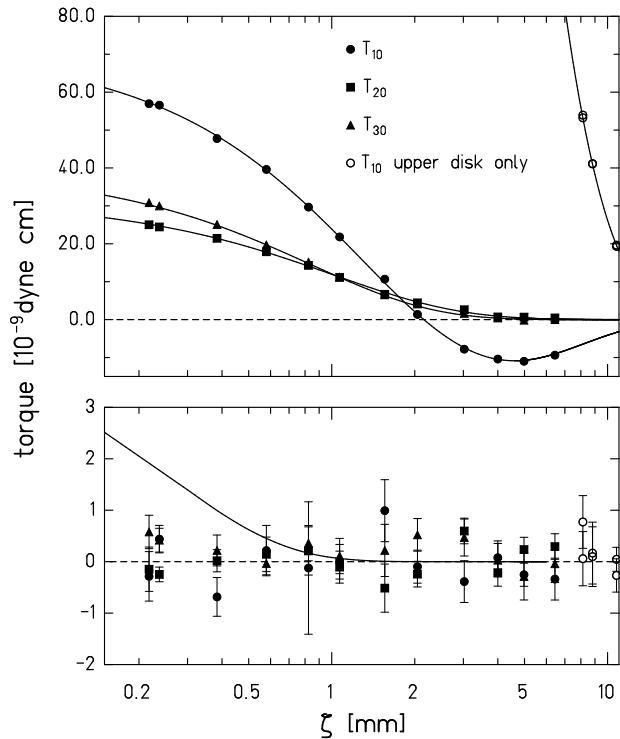


Figure 2: *Top:* Torques measured in the first experiment of Hoyle et al. as a function of pendulum/attractor separation. Open circles are data taken with the lower attractor disk removed and show the effect of uncancelled gravity. Smooth curves show the Newtonian fit. *Bottom:* Residuals for the Newtonian fit. The solid curve shows the expected residual for a Yukawa force with  $\alpha = 3$  and  $\lambda = 250 \mu\text{m}$ .

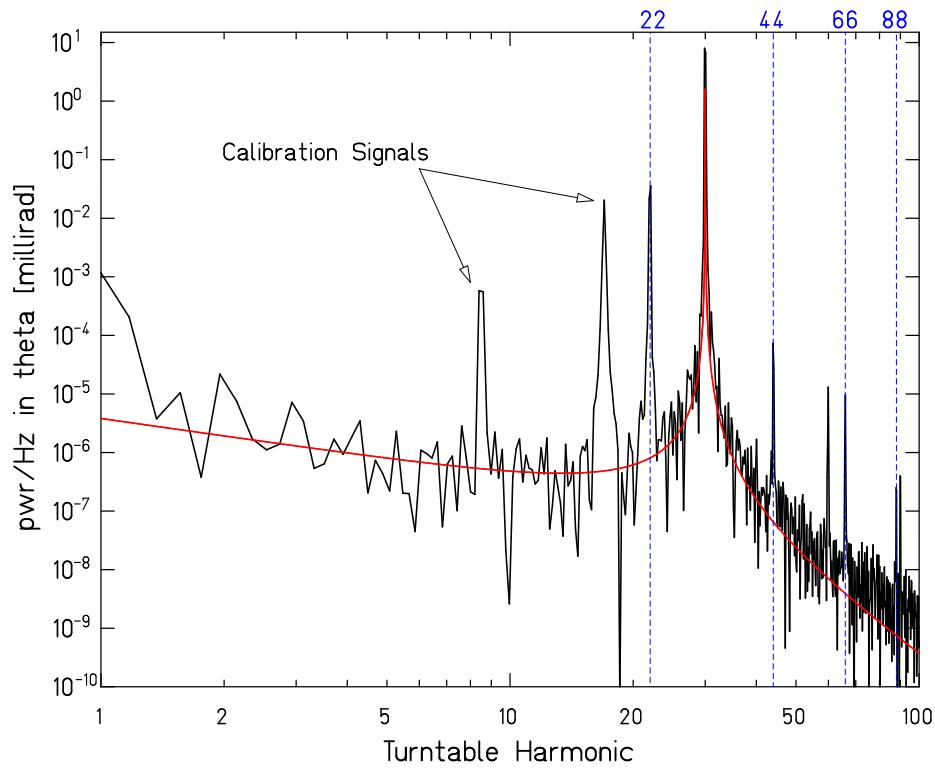


Figure 3: Spectral density of the torque signal in the 22-fold symmetric experiment of the Eöt-Wash group. The peaks at  $8.5$  and  $17 \omega$  are gravitational calibrations; the fundamental and first three overtones of the short-range signal are at  $22, 44, 66$ , and  $88 \omega$ . The smooth curve shows the thermal noise computed using Equation 33.

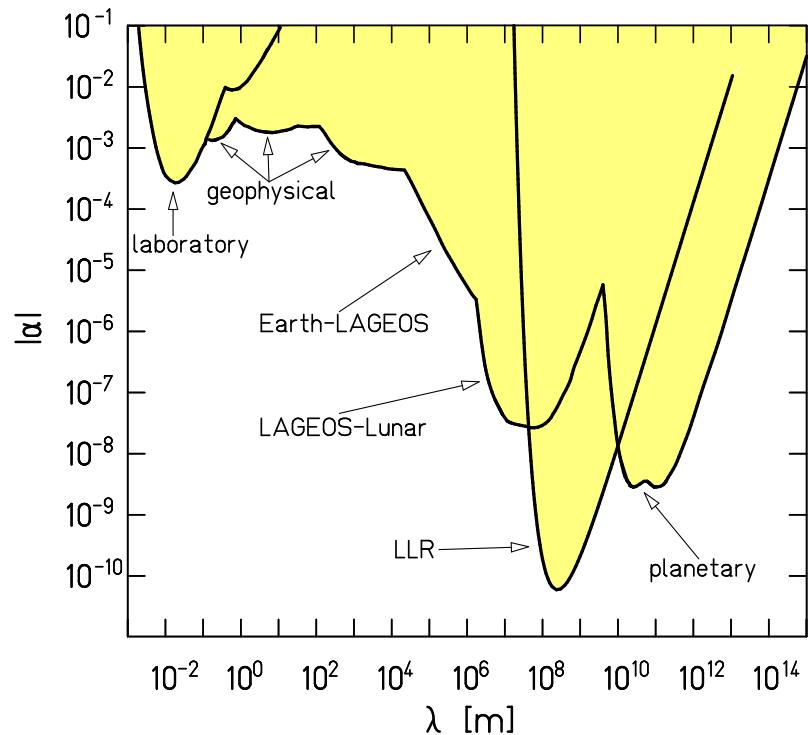


Figure 4: 95%-confidence-level constraints on ISL-violating Yukawa interactions with  $\lambda > 1$  cm. The LLR constraint is based on the anomalous perigee precession; the remaining constraints are based on Keplerian tests. This plot is based on Figure 2.13 of Reference (14) and updated to include recent LLR results.

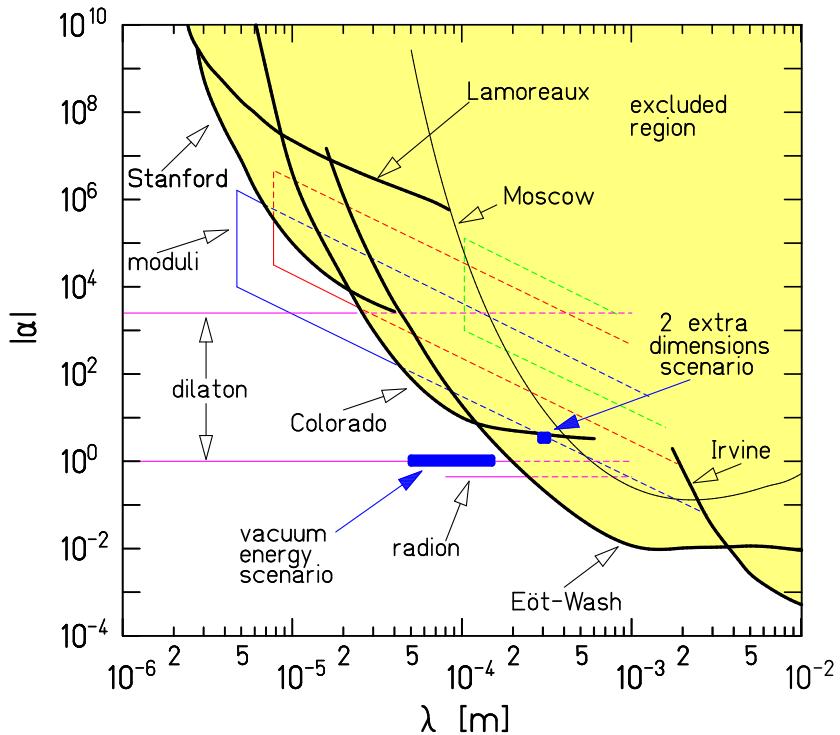


Figure 5: 95%-confidence-level constraints on ISL-violating Yukawa interactions with  $1 \mu\text{m} < \lambda < 1 \text{ cm}$ . The heavy curves give experimental upper limits (the Lamoreaux constraint was computed in Reference (151)). Theoretical expectations for extra dimensions (56), moduli (101), dilaton (102), and radion (83) are shown as well.

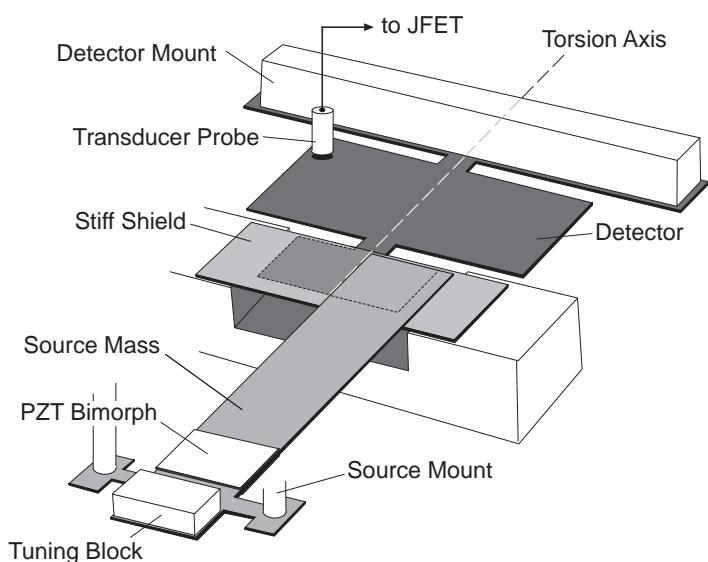


Figure 6: Schematic diagram of the instrument used by Long et al. (141).

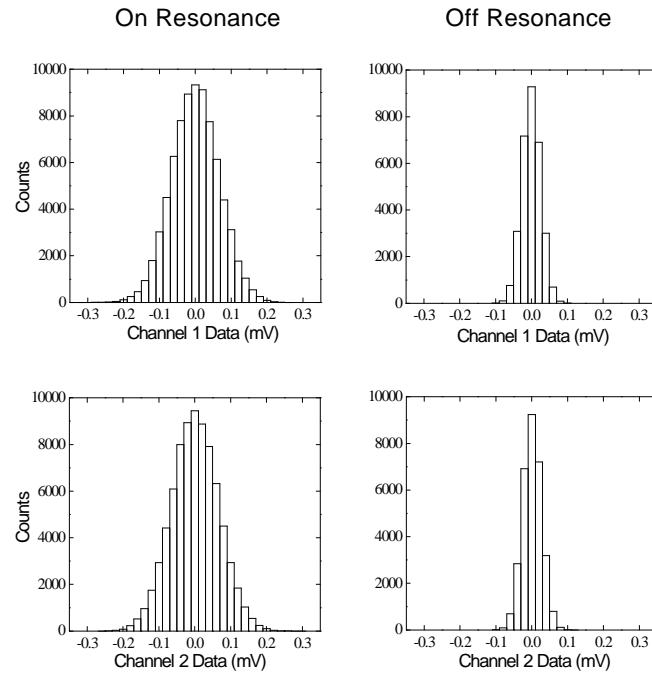


Figure 7: Data from the experiment of Long et al. (141) showing the two quadrature signals from the torsion oscillator.

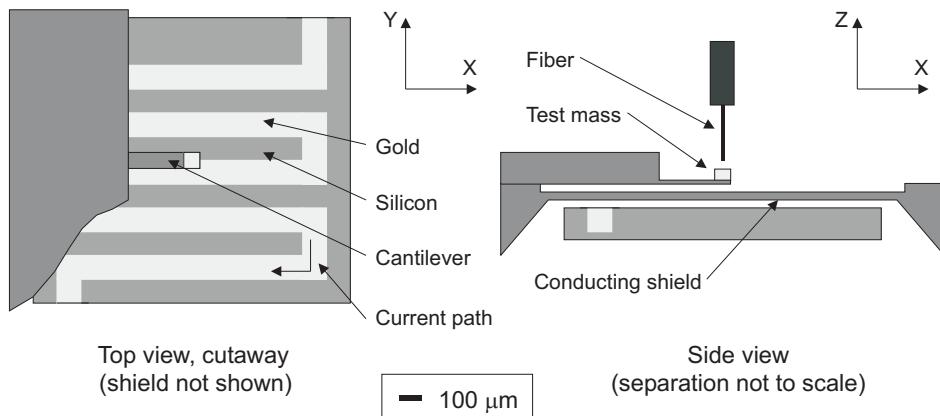


Figure 8: Schematic diagram of the instrument used by Chiaverini et al. (152).

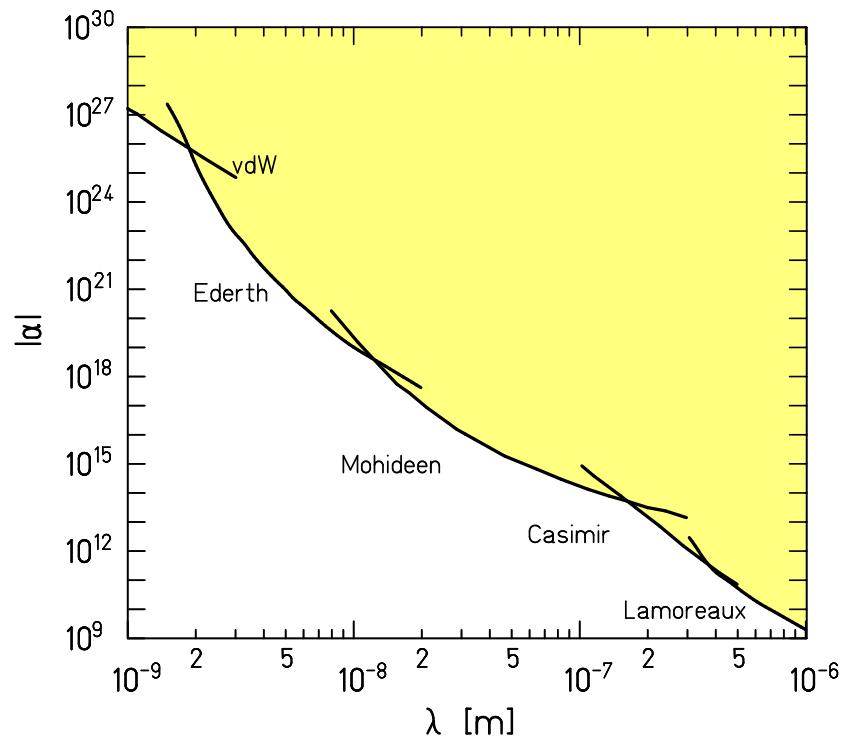


Figure 9: Constraints on ISL-violating Yukawa interactions with  $1\text{nm} < \lambda < 1\mu\text{m}$  adapted from Reference (7). As discussed in the text, these upper limits, extracted from Casimir-force measurements, are not as rigorous as those in Figures 5 and 4.

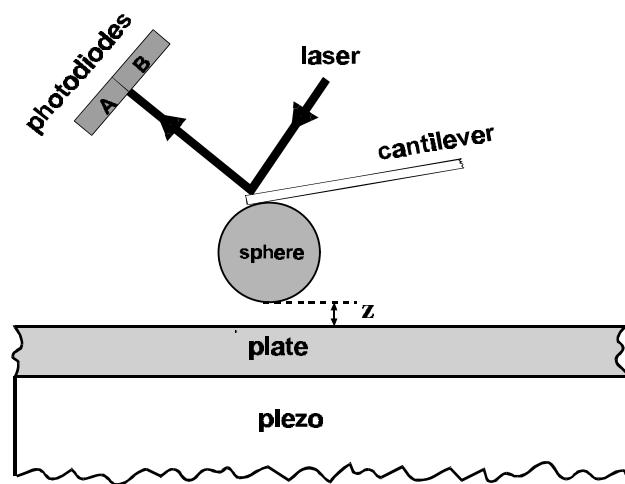


Figure 10: Schematic diagram of the Casimir-force apparatus used in Reference (165).